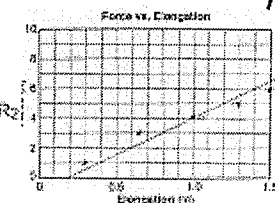
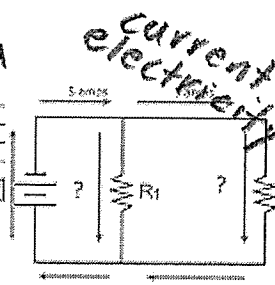
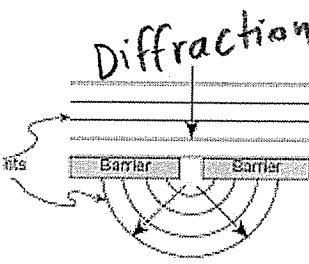
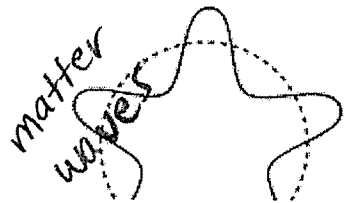
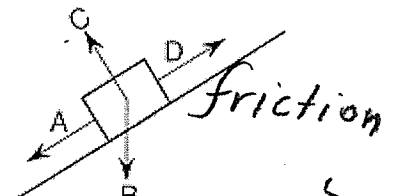
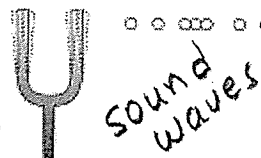
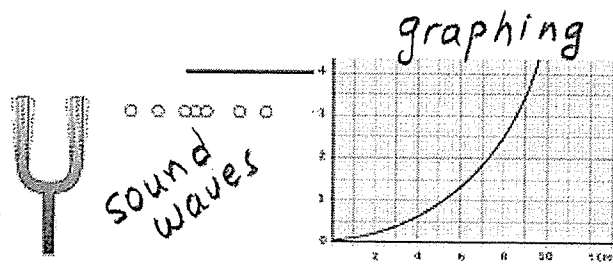
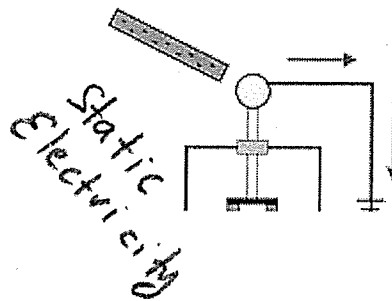
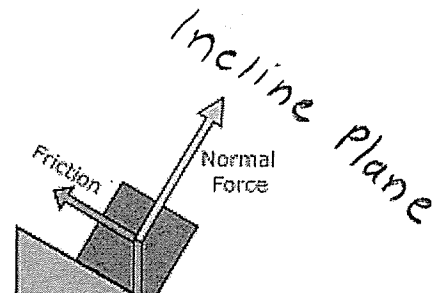
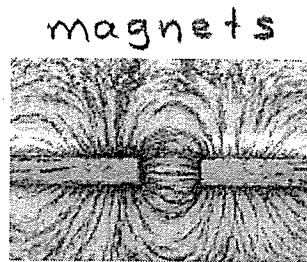
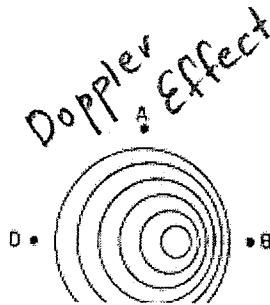
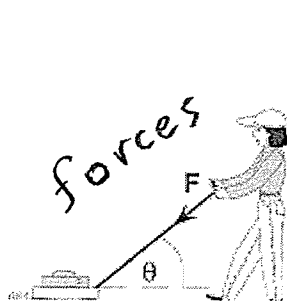
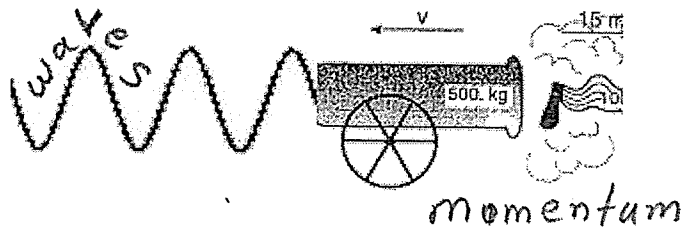
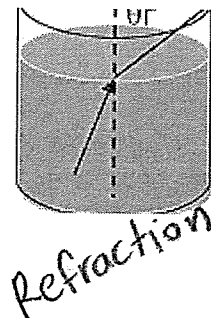
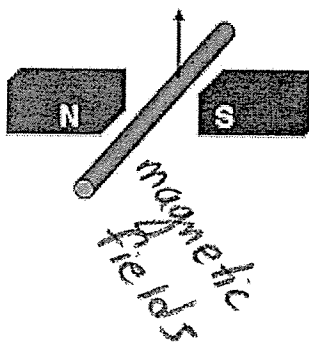


PHYSICS REVIEW

FOR THE REGENTS



Springs



momentum

BY MRS. KOUNDI

Review of Kinematics

Uniform motion with constant velocity

$$\bar{v} = \frac{d}{t} \quad \text{average speed} = \frac{\text{total distance}}{\text{total time}} \quad \text{average velocity} = \frac{\text{total displacement}}{\text{total time}}$$

Uniform motion with constant acceleration

$$a = \frac{v_f - v_i}{t}$$

$$v_f = v_i + at$$

$$\bar{v} = \frac{v_i + v_f}{2}$$

$$d = v_i t + \frac{1}{2} at^2$$

$$v_f^2 = v_i^2 + 2da$$

a is (+) when object accelerates in positive direction
or " " decelerates in negative direction

a is (-) when object accelerates in negative direction
or " " decelerates in positive direction

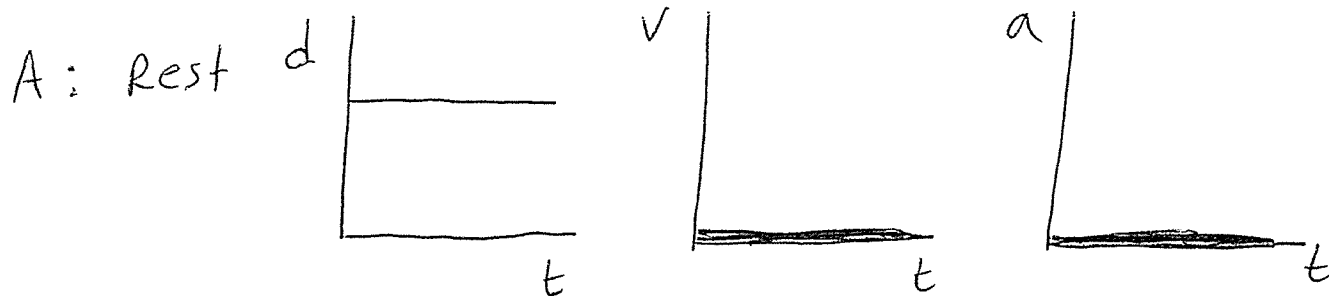
Free Fall ($a = g = -9.8 \text{ m/s}^2$)

$v_i = 0$ d is negative v_f is negative

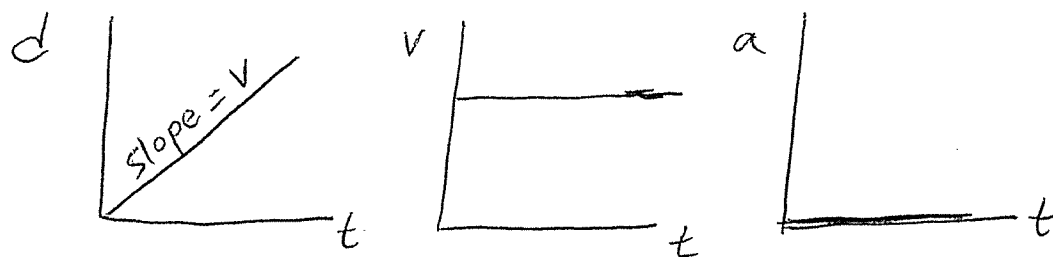
Upward Motion ($a = g = -9.8 \text{ m/s}^2$)

$v_f = 0$ d is positive v_i is positive

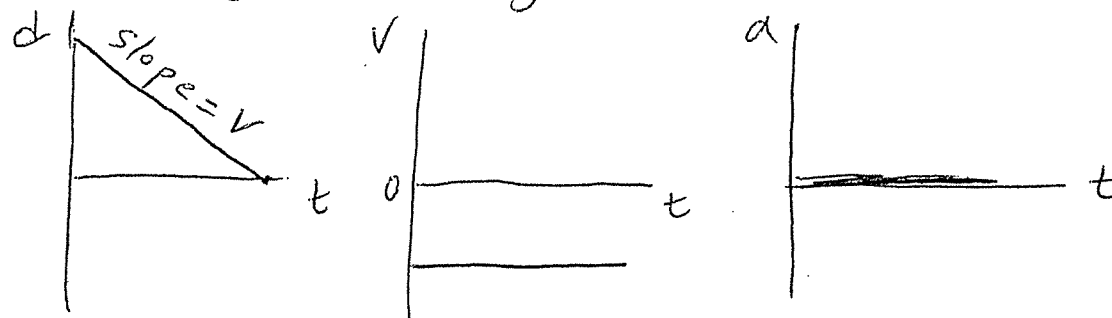
Review 8 Graphing Motion (d, v and a graphs)



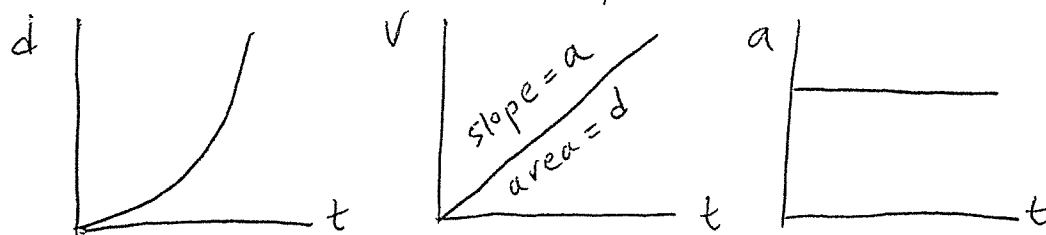
B: Constant velocity in a positive direction



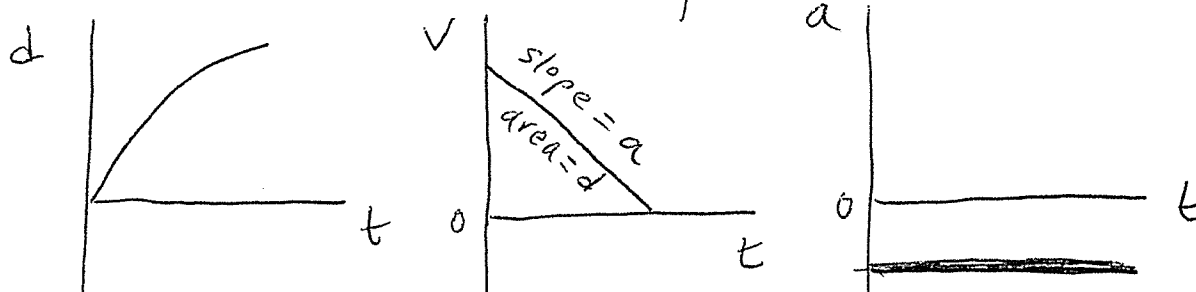
C: Constant velocity in a negative direction



D: Accelerated Motion in a positive direction

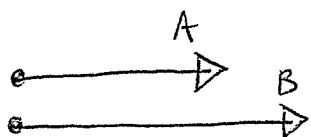


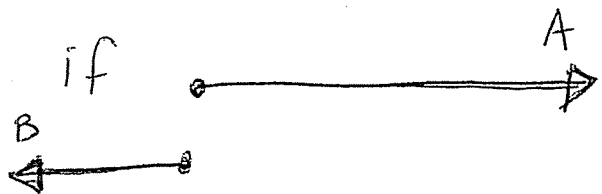
E: Decelerated Motion in a positive direction

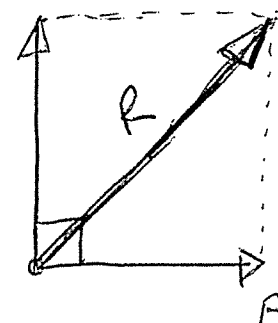


Review: Statics

Vectors (adding and resolving vectors)

if  are parallel and 0° apart $R = A + B$ R is (max)

if  are parallel and 180° apart $R = A - B$ R is (min)

if  are perpendicular or 90° apart $R = \sqrt{A^2 + B^2}$

* R : Resultant: the result of two or more vectors combining

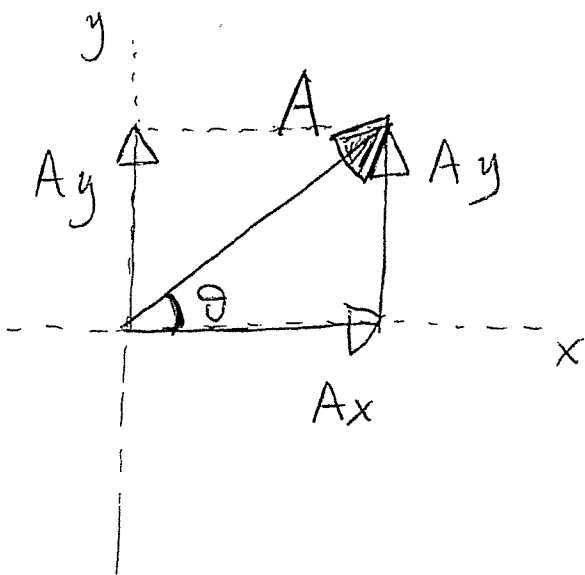
Resultant Range

$$|A| - |B| \leq R \leq |A| + |B|$$

or

$$R_{\min} \leq R \leq R_{\max}$$

example
two vectors
 $A = 5\text{m}$, $B = 7\text{m}$
 $2\text{m} \leq R \leq 12\text{m}$



Components

$$A_x = A \cos \theta$$

$$A_y = A \sin \theta$$

$$\theta = \tan^{-1} \left(\frac{A_y}{A_x} \right)$$

horizontal angle

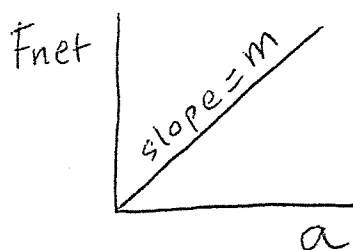
$$A = \sqrt{A_x^2 + A_y^2}$$

Newton's Laws

1. $m \sim \text{Inertia}$ (the more the mass, the greater the inertia)

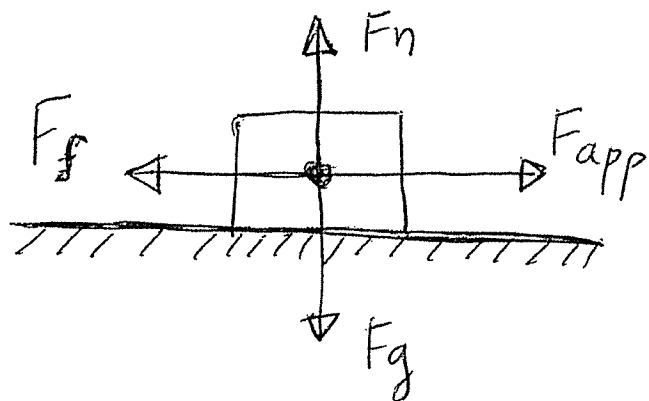
2. $F_{\text{net}} = m a$

3. $F_{\text{action}} = F_{\text{reaction}}$

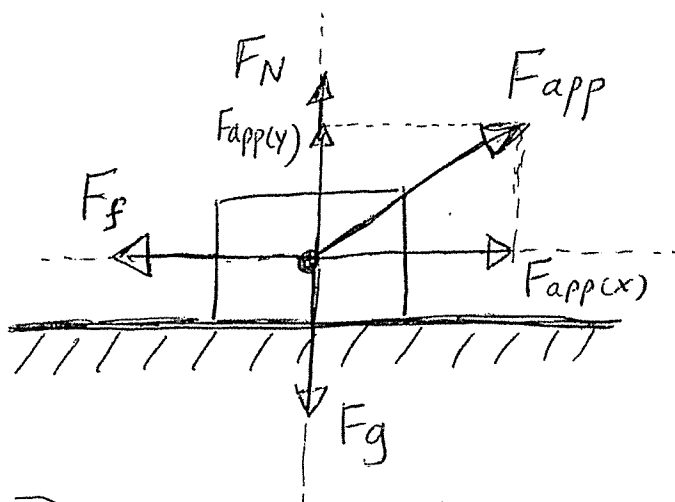


Friction ($F_{\text{static}} > F_{\text{kinetic}}$) and Free Body Diagrams

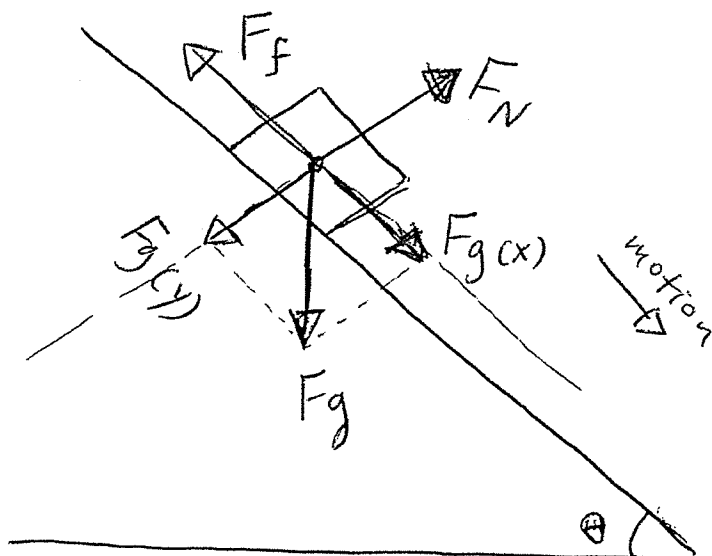
$F_f = \mu F_N$



$F_{\text{net}} = F_{\text{app}} - F_f$



$F_{\text{net}} = F_{\text{app}(x)} - F_f$



Incline Plane (downward motion)

$F_{gx} = F_g \sin \theta$

$F_{gy} = F_g \cos \theta$

if motion is constant

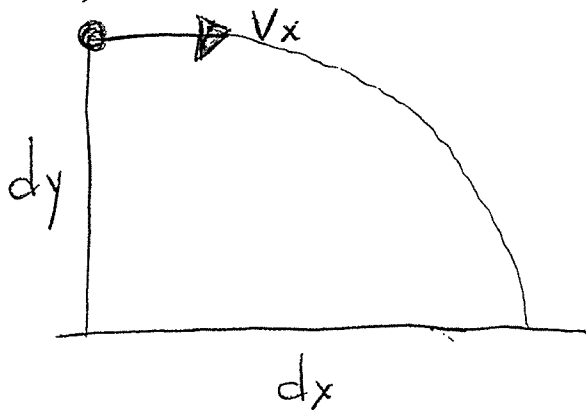
$F_f = F_{gx}$ and

$F_N = F_{gy}$

Review

Projectile Motion

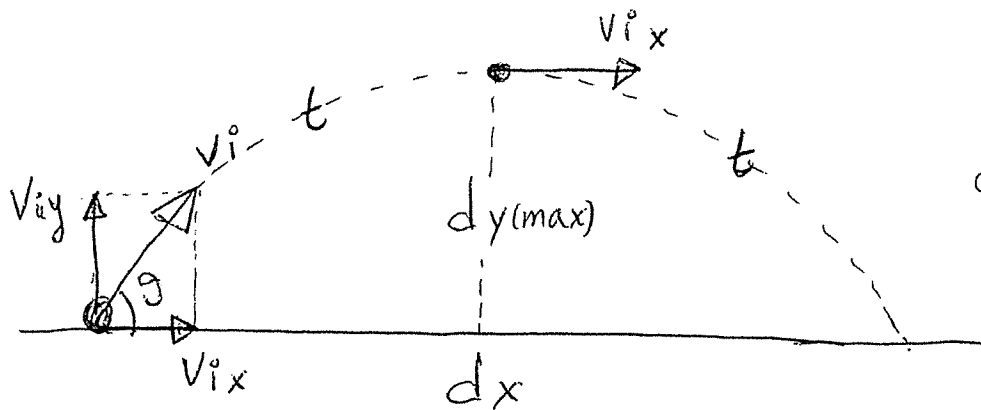
A) Horizontal



$$V_x = \frac{dx}{t}$$

$$dy = \frac{1}{2} g t^2$$

B) Fired at an angle θ



$$v_{ix} = v_i \cos \theta$$

$$v_{iy} = v_i \sin \theta$$

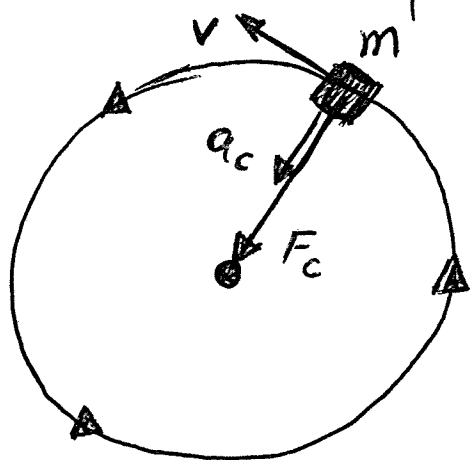
$$dx = v_{ix} \cdot 2t$$

$$dy(\max) = \frac{1}{2} g t^2$$

$$v_{iy} = g t \quad g = -9.8 \frac{m}{s^2}$$

- As angle θ increases dy increases and dx decreases
- max range (dx) occurs at $\theta = 45^\circ$
- Complementary angles produce the same range (dx).
(sum of 90°)
- Max altitude (dy) occurs at $\theta = 90^\circ$
- Mass of the object does not affect the dy or dx
- Air Resistance decreases dy and dx and time
- As dy increases, time increases ($dy \sim t$)

Review : Centripetal Force



$$v = \frac{2\pi r}{T}$$

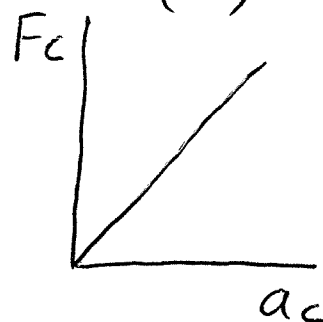
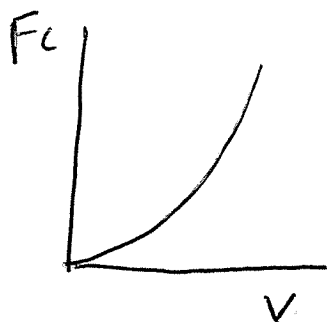
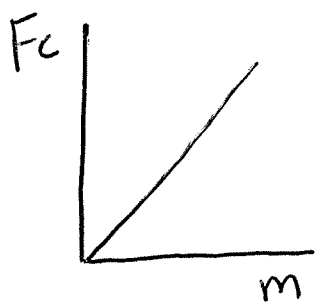
T : period of Revolution
(time to complete one circle)

$$a_c = \frac{v^2}{r}$$

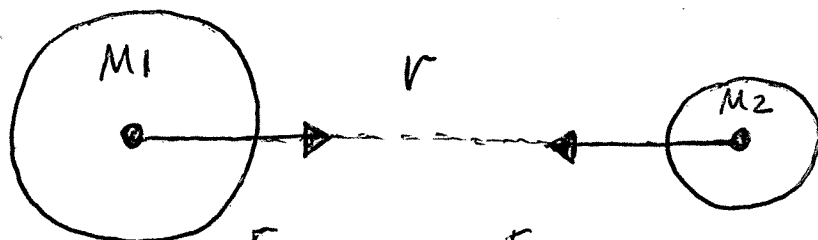
$$F_c = m a_c$$

$$F_c = \frac{mv^2}{r}$$

$$F_c = \frac{(\quad)(\quad)^2}{(\quad)}$$



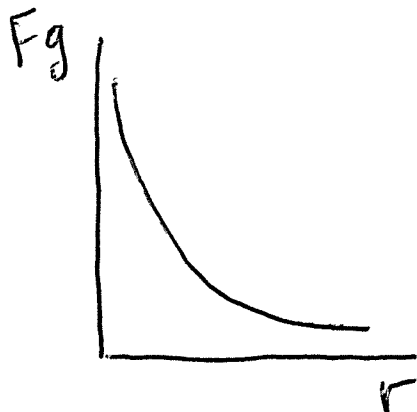
Review : Law of Universal Gravity



$$F_g(1,2) = F_g(2,1)$$

$$F_g = \frac{G M_1 M_2}{r^2}$$

$$F_g = \frac{(\quad)(\quad)}{(\quad)^2}$$



r	2	3	4	$\frac{1}{2}$	$\frac{1}{3}$	$\frac{1}{4}$
F_g	$\frac{1}{4}$	$\frac{1}{9}$	$\frac{1}{16}$	4	9	16

Review: Impulse - Momentum - Conservation of Momentum

$$F_{\text{net}} = m a$$

$$F_{\text{net}} = m \frac{\Delta v}{t}$$

$$F_{\text{net}} = m \frac{(v_f - v_i)}{t}$$

$$F_{\text{net}} \cdot t = m v_f - m v_i$$

$$J = p_f - p_i$$

$$J = \Delta p$$

$$* p = m v$$

$$p_i = m v_i$$

$$p_f = m v_f$$

$$* J = \Delta p$$

$$J = F_{\text{net}} \cdot t$$

$$* F_{\text{net}} t = F_{\text{net}} t$$

extending
the time of
a collision
minimizes
the force

Collisions

1) Elastic

$$m_1 v_1 + m_2 v_2 = m_1 v_1' + m_2 v_2'$$

2) Inelastic

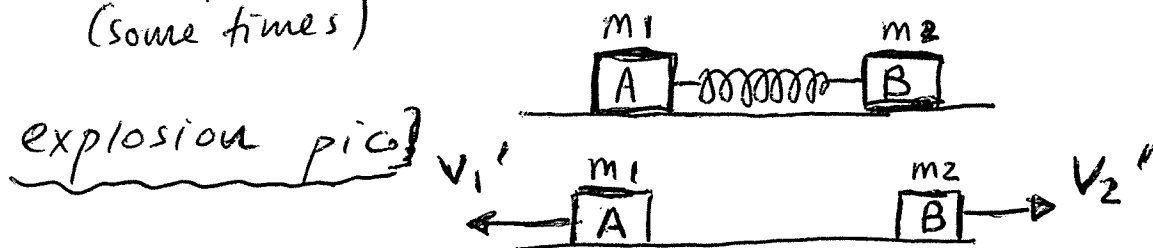
$$m_1 v_1 + m_2 v_2 = (m_1 + m_2) v'$$

3) Explosion

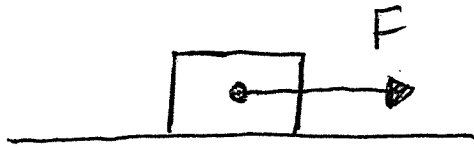
$$0 = m_1 v_1' - m_2 v_2'$$

4) Computation
(some times)

$$(m_1 + m_2) v = m_1 v_1' + m_2 v_2'$$



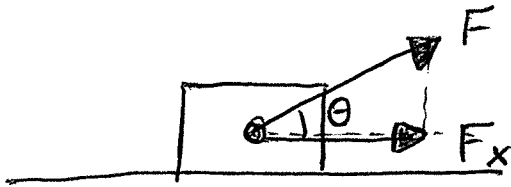
Energy - Work - Power - Conservation of Energy



$$W = F \cdot d \quad (N \cdot m = \text{Joule})$$

$$* \text{ Joule} = N \cdot m = \text{kg} \frac{m}{s^2} \cdot m = \text{kg} \frac{m^2}{s^2}$$

only F_x does work



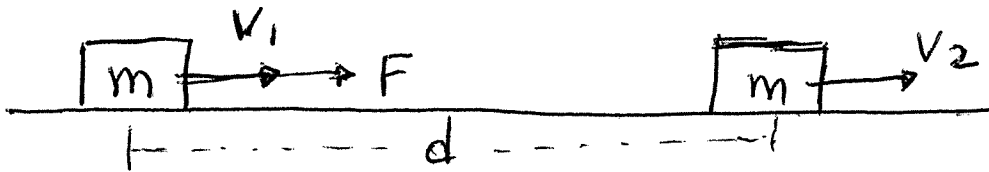
$$W = F_x \cdot d = F \cos \theta \cdot d$$

* Work can be done only when F and d are having the same direction and neither one is zero.

Power: Rate of doing work $P = \frac{W}{t} = \frac{F \cdot d}{t} = F \cdot \bar{v}$

$$* \text{ unit: } \text{Watt} = \frac{\text{Joule}}{\text{sec}} = \frac{N \cdot m}{s} = \frac{\text{kg} \frac{m}{s^2} \cdot m}{s} = \text{kg} \frac{m^2}{s^3}$$

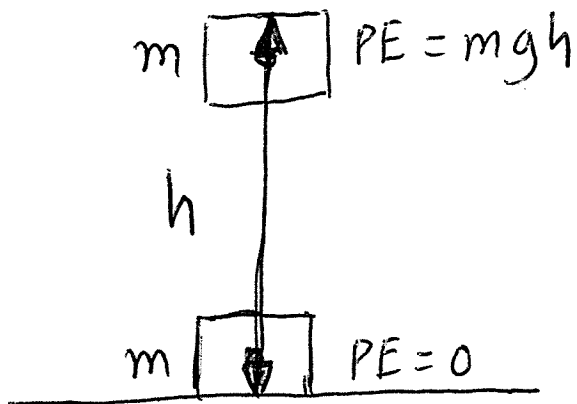
Work / Kinetic Energy Theorem



$$\text{Work} = F \cdot d = \frac{1}{2} m v_2^2 - \frac{1}{2} m v_1^2$$

* the work done by the Force to accelerate the mass is equal to the change of the kinetic energy of the object

Work done during lifting is

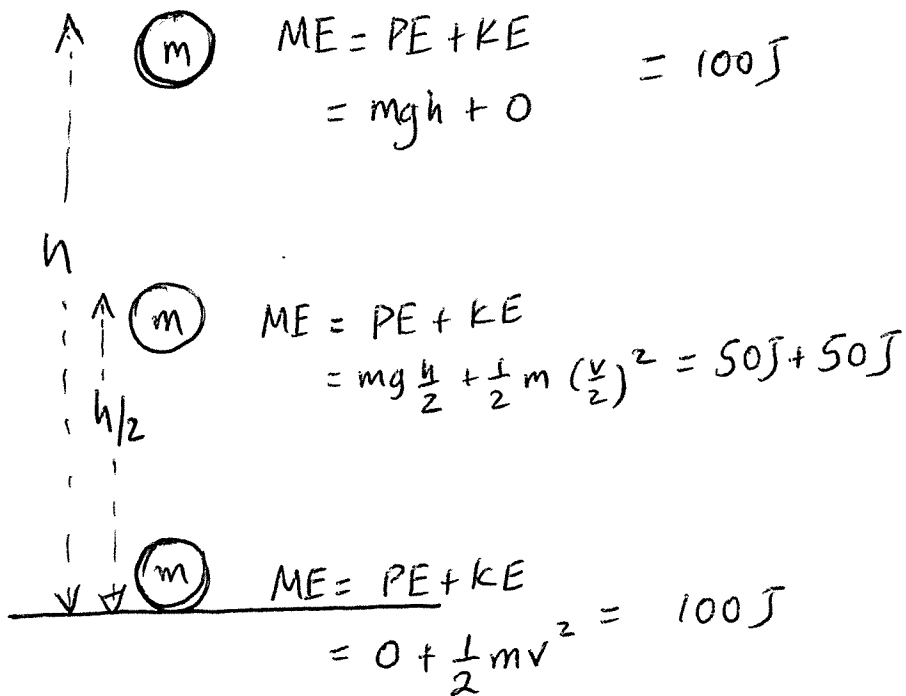


$$W = F_g \cdot h = \Delta PE$$

$$mgh = mgh - 0$$

the work done by the Force of Gravity

Free Fall.

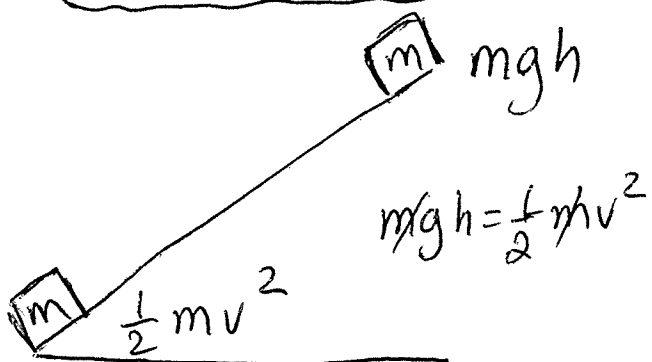


$$mgh = \frac{1}{2}mv^2$$

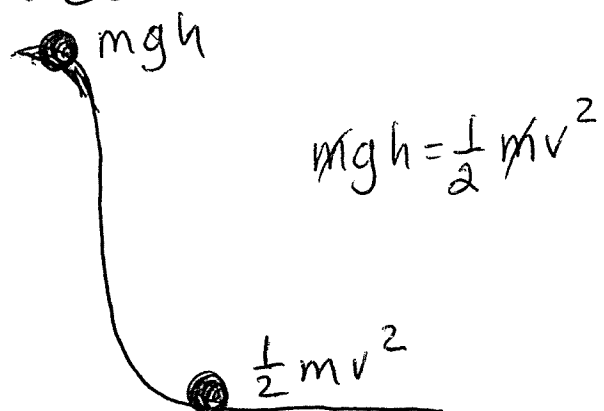
$$2gh = v^2$$

$$v = \sqrt{2gh}$$

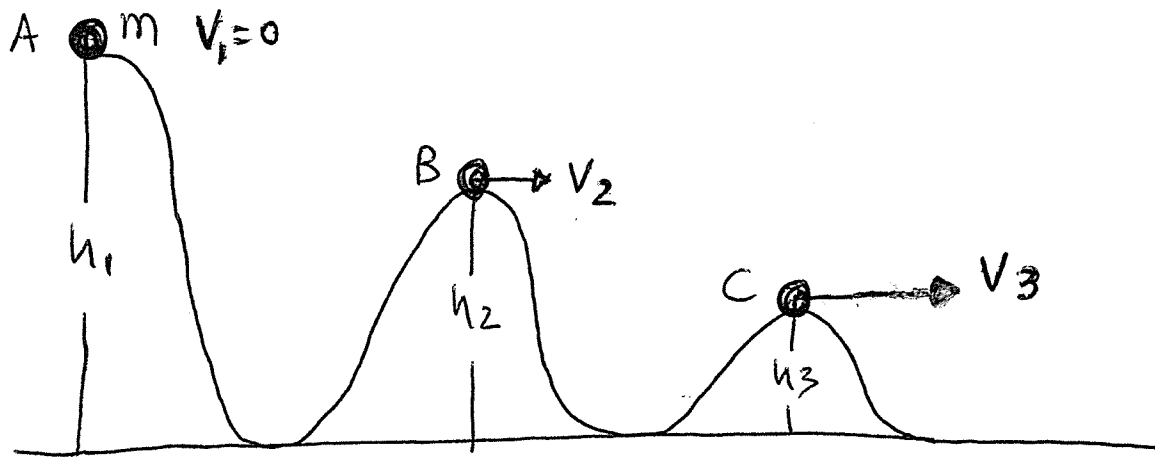
Incline Planes



Roller Coasters



More Roller Coasters



A: $ME = mgh_1 + 0$

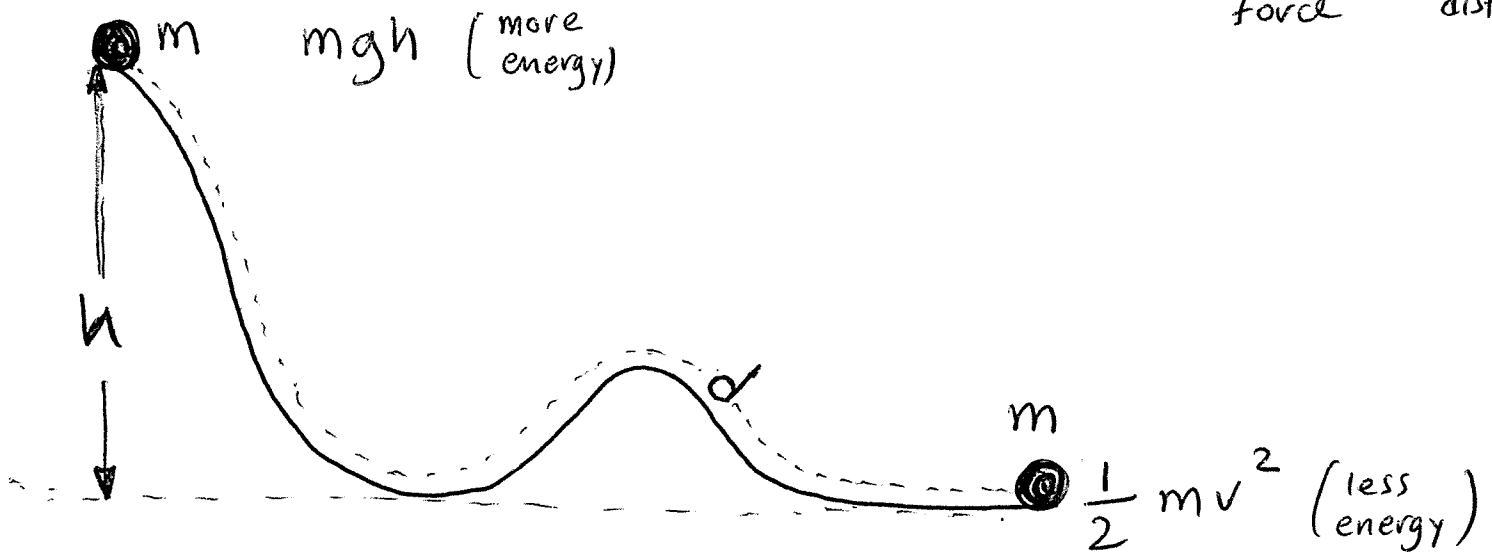
B: $ME = mgh_2 + \frac{1}{2}mv_2^2$

C: $ME = mgh_3 + \frac{1}{2}mv_3^2$

* As height decreases
~~PE~~ decreases and
~~KE~~ increases
 $(v_3 > v_2 > v_1)$
 $(h_3 < h_2 < h_1)$

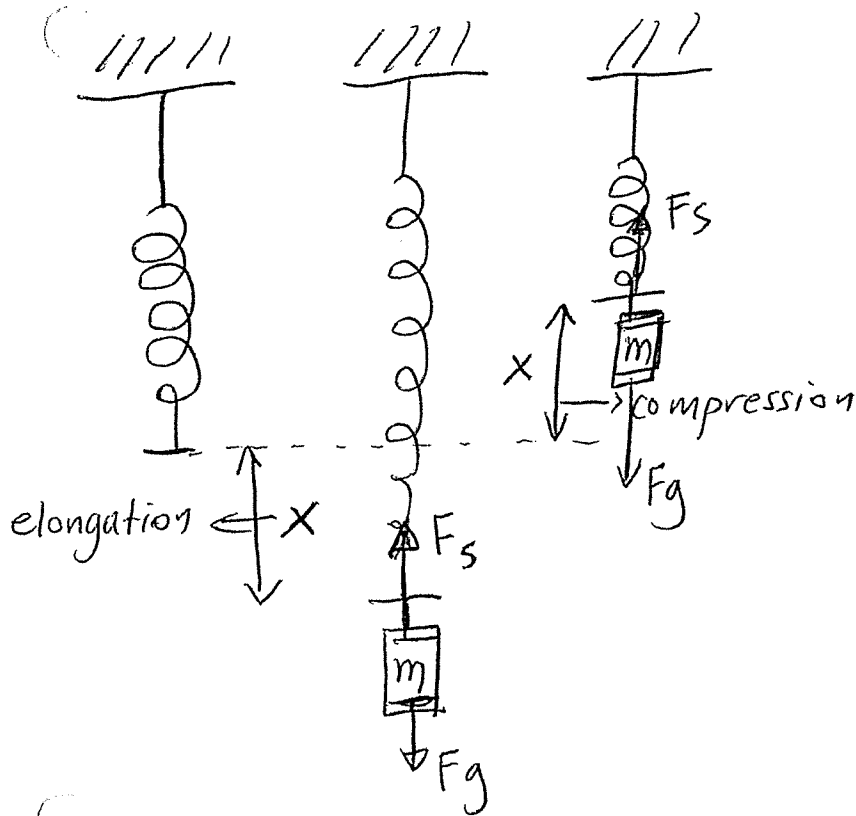
In Non-Ideal systems (where friction exists)

Work of friction = heat = $f \cdot d$ = friction force $\cdot$ total distance



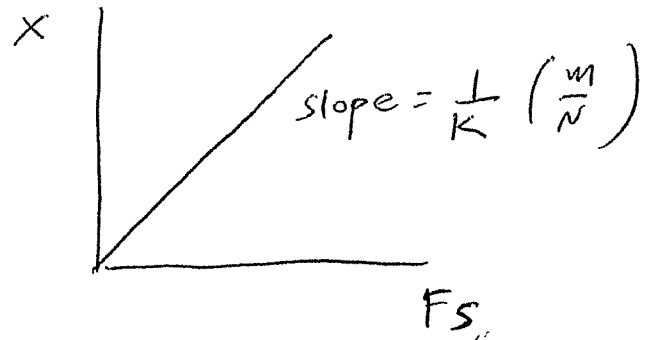
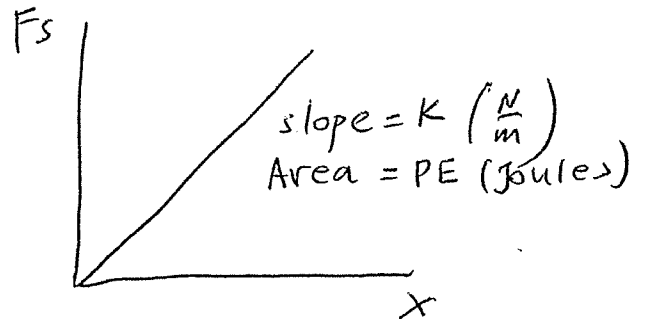
$$W_f = f \cdot d = mgh - \frac{1}{2}mv^2$$

Springs



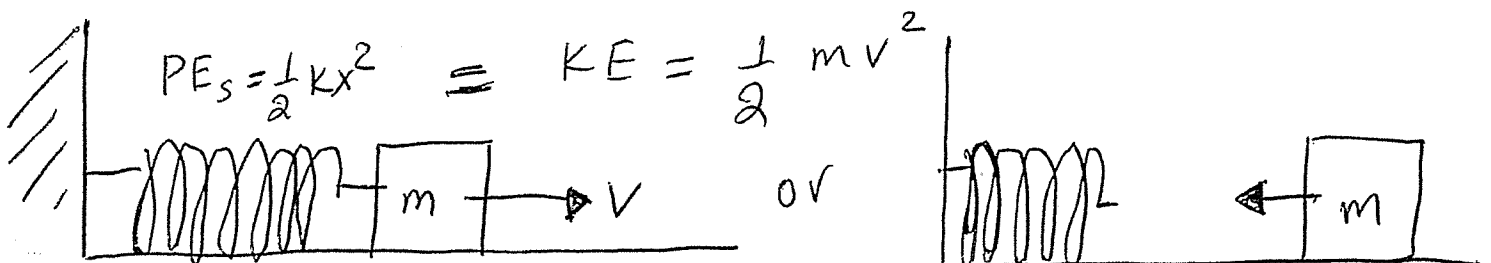
$$F_s = kx \quad (N)$$

$$PE_s = \frac{1}{2} kx^2 \quad (\text{Joules})$$

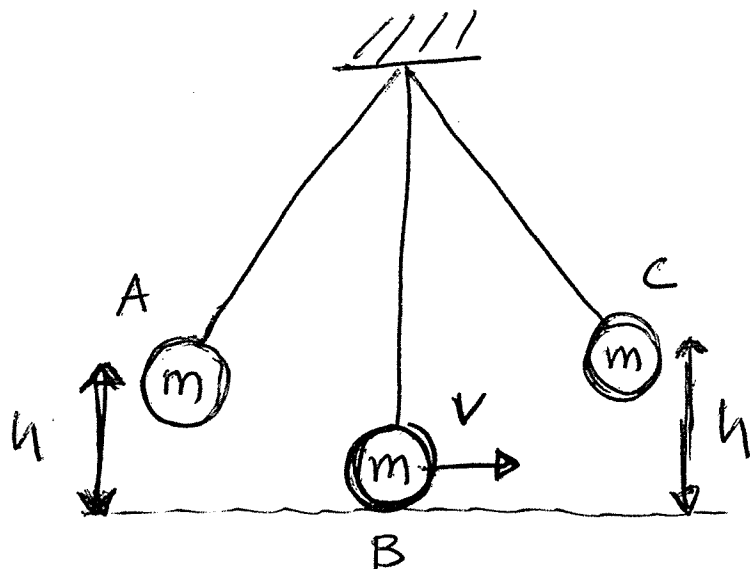


$$PE_s = \frac{1}{2} kx^2 \quad \text{or}$$

$$\frac{1}{2} F_s \cdot x \quad (\text{in Joules})$$



Energy Conservation in the pendulum



$$A: ME = KE + PE = 0 + mgh$$

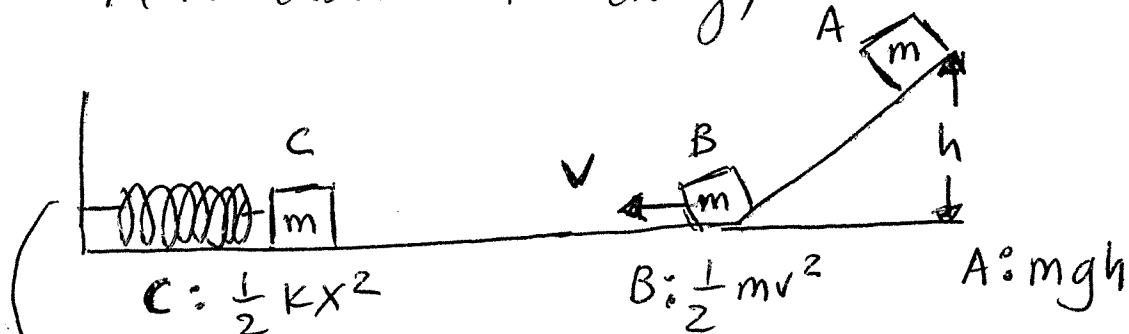
$$B: ME = KE + PE = \frac{1}{2}mv^2 + 0$$

$$C: ME = KE + PE = 0 + mgh$$

$$ME(A) = ME(B) = ME(C)$$

$$\frac{1}{2}mv^2 = mgh$$

More cases with Energy Conservation and spring.



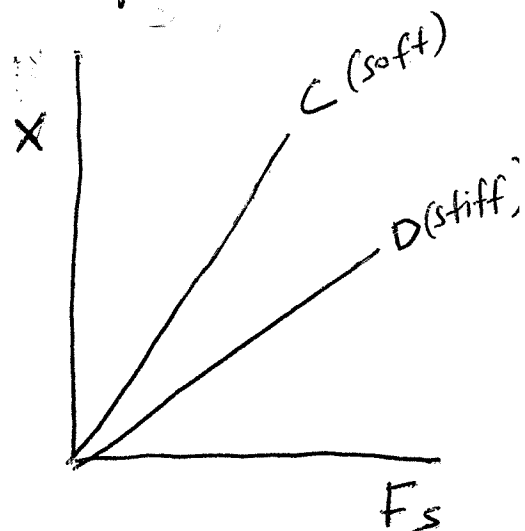
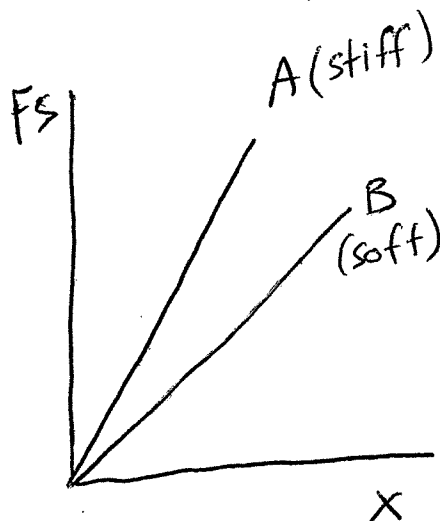
$$C: \frac{1}{2}kx^2$$

$$B: \frac{1}{2}mv^2$$

$$A: mgh$$

$$mgh = \frac{1}{2}mv^2 = \frac{1}{2}kx^2$$

Multiple springs (compare spring constants)



Static Electricity (Notes)

charge of an electron (e) = $-1.6 \times 10^{-19} \text{ C}$

charge of a proton (p) = $+1.6 \times 10^{-19} \text{ C}$

elementary charge = charge of the e or p = $1.6 \times 10^{-19} \text{ C}$

1 Coulomb (C) - unit of charge = $6.25 \times 10^{18} e$

* 1 μC = 10^{-6} C

A positive charge - lost electrons (e)

A negative charge - gained electrons (e)

Only electrons move

Transfer of electrons

Rubber + fur (Rubber gains e and becomes $-$)
(fur loses e and becomes $+$)

Glass + Silk (Glass loses e and becomes $+$)
(silk gains e and becomes $-$)

Elementary Charge

Every charge is a multiple integer of the elementary charge $Q = n e$ $n = 1, 2, 3, 4, \dots$

ex. Could $3.2 \times 10^{-19} \text{ C}$ be a real charge

$$\frac{3.2 \times 10^{-19} \text{ C}}{1.6 \times 10^{-19} \text{ C}} = 2e \quad \text{Yes}$$

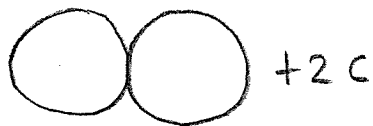
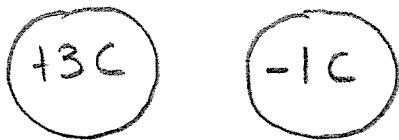
ex could $5 \times 10^{-19} \text{ C}$ be a real charge

$$\frac{5 \times 10^{-19} \text{ C}}{1.6 \times 10^{-19} \text{ C}} = 3.125e \quad \text{Not possible}$$

Conservation of charge:
come in contact and then
total charge gets evenly

When two or more charged objects
get separated, the
distributed between them.

ex



+2C



ex

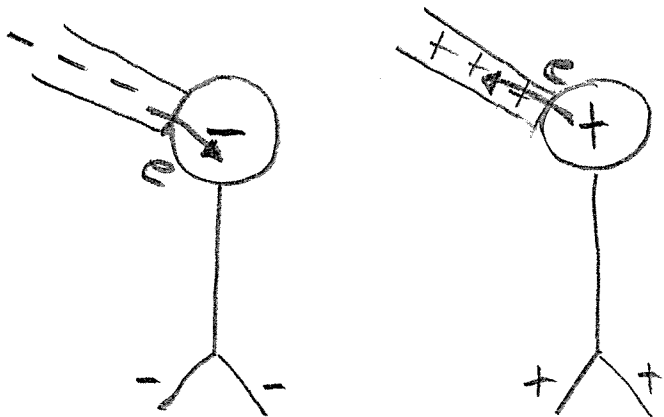


12e

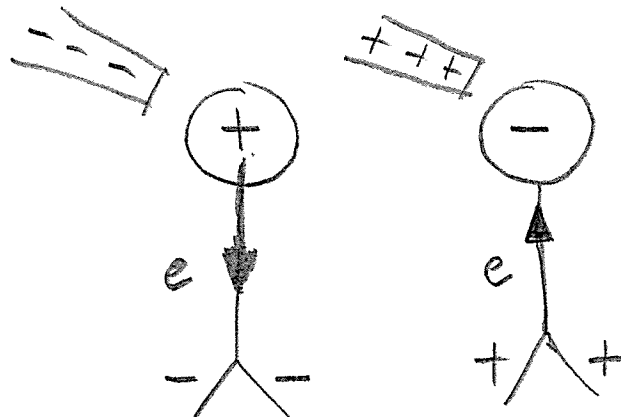


Electroscope

Conduction



Induction



Coulomb's Law



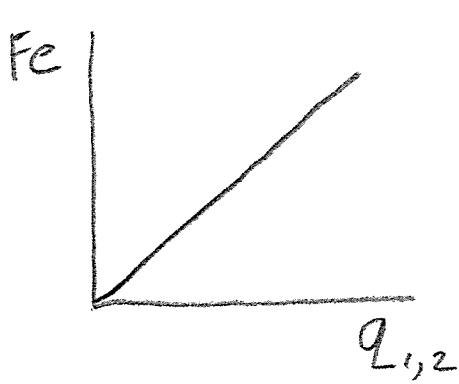
$$F_e = \frac{k q_1 q_2}{d^2}$$

$$k = 9 \times 10^9 \frac{\text{Nm}^2}{\text{C}^2}$$

if $q_1(\pm)$ and $q_2(\pm)$ then $F_e (+)$ repulsive force
if $q_1(+)$ and $q_2(-)$ then $F_e (-)$ attractive force

Coulomb's Law → cont

find patterns

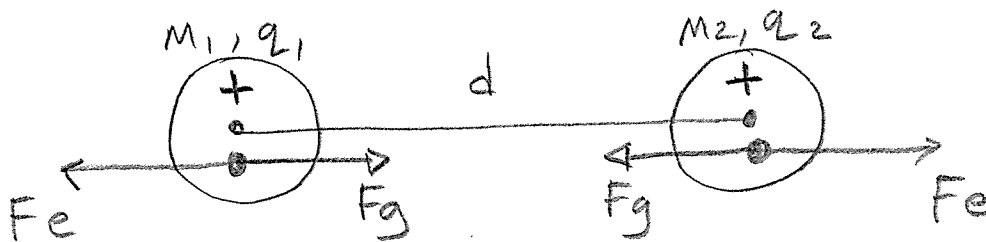


ex.

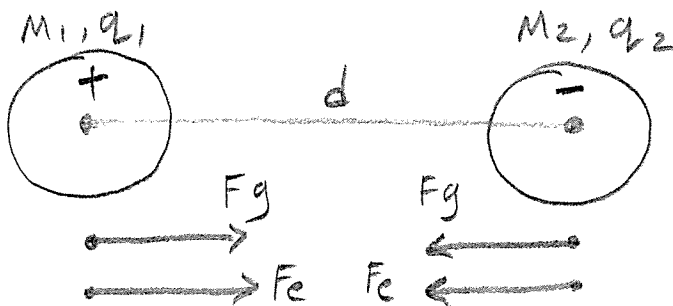
$$F_e = \frac{(\quad)(\quad)}{(\quad)^2}$$

Compare Electric with Gravitational forces

if



if



* Vectors are not drawn to scale

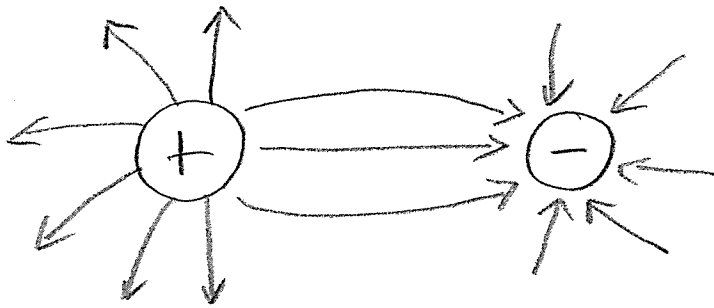
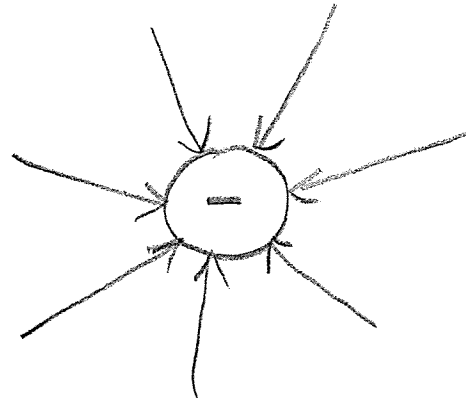
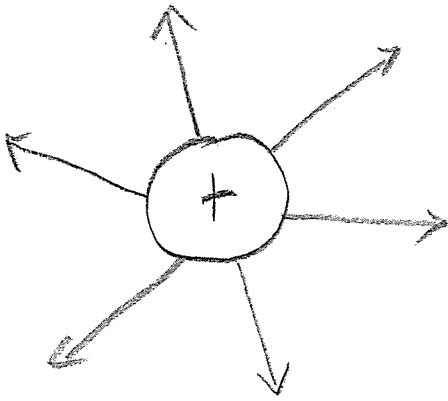
F_g is much less than F_e stronger force

F_g : always an attractive force

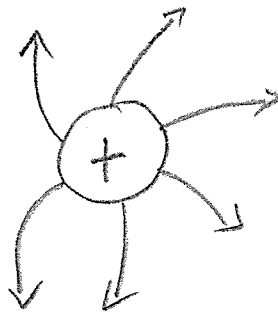
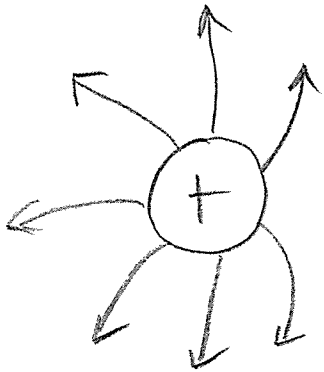
F_e : can be attractive or repulsive

but F_e is stronger than F_g

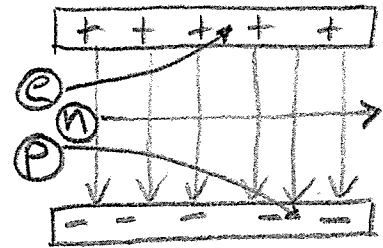
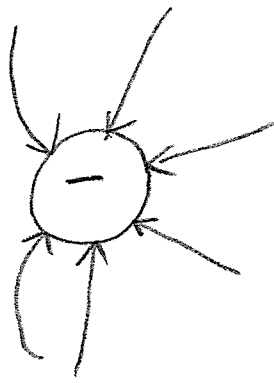
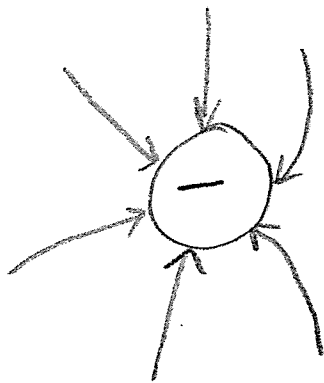
Electric Field Lines * (never intersect)



attractive field



Uniform Electric Field between two parallel plates oppositely charged

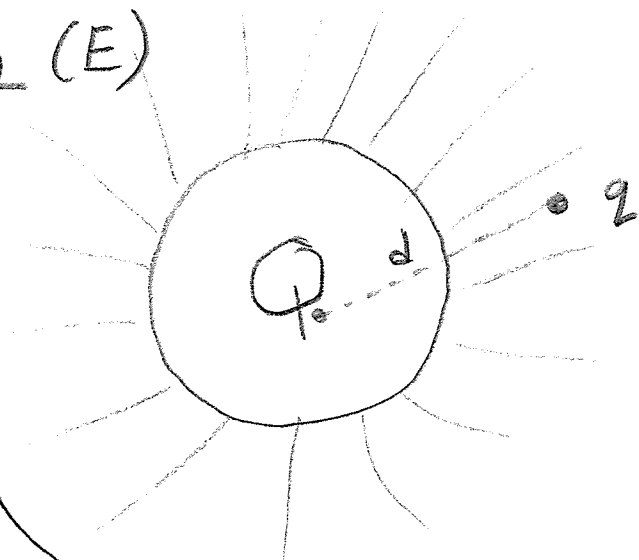
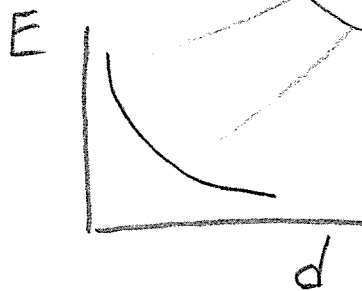
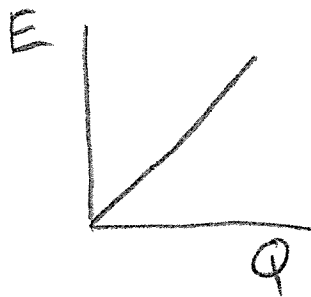


* everywhere in the field the intensity or strength is the same

Electric Field Strength (E)

$$E = \frac{F_e}{q} = \frac{\frac{kQq}{d^2}}{q} = \frac{kQ}{d^2}$$

Unit: $\frac{N}{C}$



Electric Potential Difference (V or Voltage)

$$V = \frac{W}{q}$$

W: work done on a charge q to either keep it in the electric field or move it away

Unit: Volt = $\frac{\text{Joule}}{\text{Coulomb}}$

$$1V = 1 \frac{J}{C}$$

Review Conversions on Units

Charge:
Q

$$e \xrightarrow[\div (1.6 \times 10^{-19})]{\times 1.6 \times 10^{-19}} C$$

*when you divide with a number in scientific notation remember to of parenthesis

Electric
Work
or

$$eV \xrightarrow[\div (1.6 \times 10^{-19})]{\times 1.6 \times 10^{-19}} \text{Joule}$$

Energy
(W)

Current Electricity Notes

V: Potential Difference (Voltage)

$$V = \frac{W}{q} \quad \text{unit: Volt} = \frac{\text{Joule}}{\text{Coulomb}} \quad \text{or (V)}$$

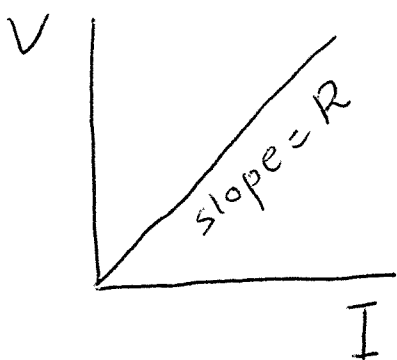
I: Electric Current

$$I = \frac{q}{t} \quad \text{unit: Ampere} = \frac{\text{Coulomb}}{\text{sec}} \quad \text{or (Amp)}$$

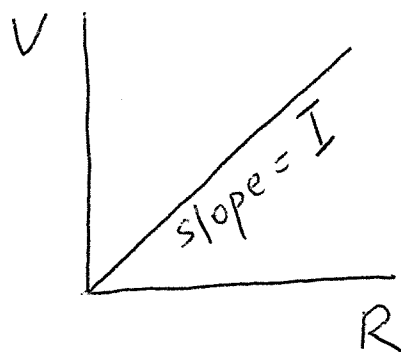
R: Electric Resistance

$$R = \frac{V}{I} \quad \text{unit: Ohm} = \frac{\text{Volt}}{\text{Ampere}} \quad \text{or } (\Omega) \text{ or } (\Omega)$$

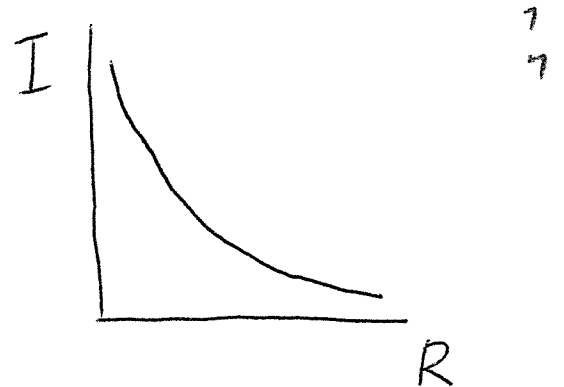
Graphs (Ohm's Law)



$$V = \boxed{R} I$$



$$V = \boxed{I} R$$



$$I = \frac{V}{R} \quad \text{or} \quad R = \frac{V}{I}$$

Electric Resistance

$$R = \frac{\rho L}{A}$$

R depends on

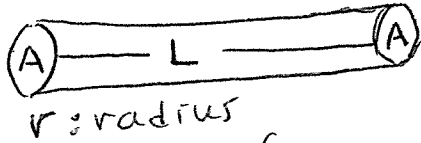
ρ : resistivity

L : length

A : Cross Sectional Area

T : Temperature

pic :



$$A = \pi r^2$$

ρ : resistivity (unit: $\Omega \cdot m$)

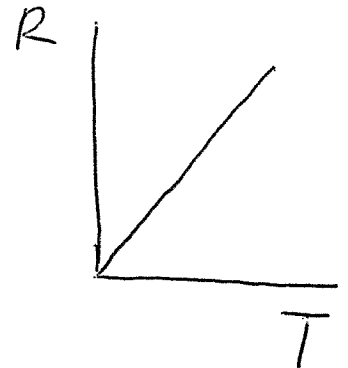
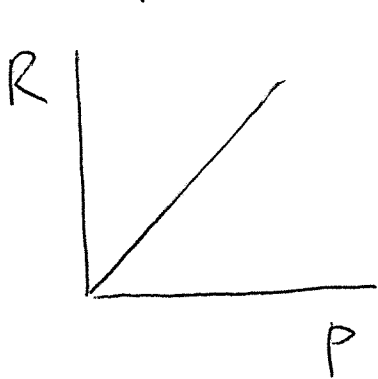
check your Ref. Tables for values of resistivity Relationship with R : direct

L : length (unit: m) Relationship with R : direct

A : Cross Sectional Area (unit: m^2) Relationship with R : inverse
(thickness)

T : Temperature Relationship with R : direct
* (only for conductors)

Graphs



Power and Energy

$$P = \frac{W}{t} \text{ or } \frac{E}{t} \rightarrow \frac{Vq}{t} = VI$$

$$\text{unit of Watt} = \frac{\text{Joule}}{\text{sec}} = \frac{\text{Volt} \cdot \text{Coulomb}}{\text{sec}} = \text{Volt} \cdot \text{Amp}$$

$$P = VI \text{ (when } R \text{ is not given)} \text{ or } \frac{V^2}{R} \text{ (when } I \text{ is not given)} \text{ or } I^2 R \text{ (when } V \text{ is not given)}$$

$$W = P \cdot t \text{ or } VI t \text{ or } \frac{V^2}{R} t \text{ or } I^2 R t$$

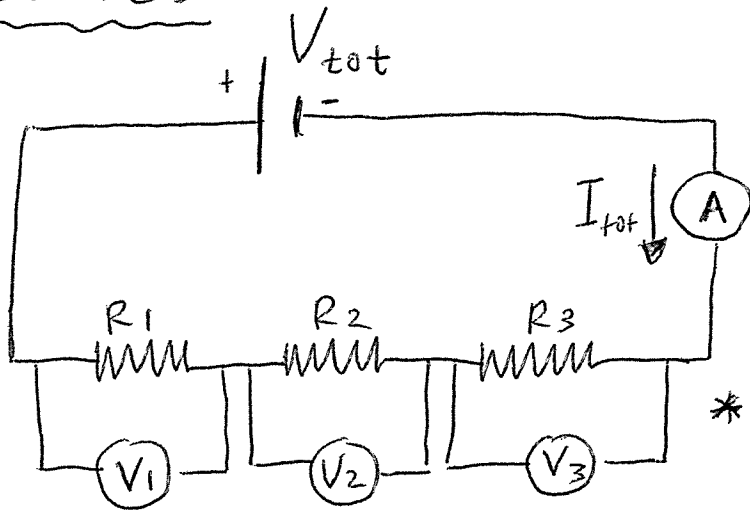
$$\text{unit of Joule} = \text{Watt} \cdot \text{sec}$$

$$\text{unit of work (or Electric Energy)} = \text{KWh}$$

$$\begin{aligned} 1 \text{ KWh} &= 1000 \text{ Watt} \cdot 3,600 \text{ sec} = \\ &= 3,600,000 \text{ Watt} \cdot \text{sec} \\ &= 3,600,000 \text{ Joules} \end{aligned}$$

Circuits

Series



$$I_{tot} = I_1 = I_2 = I_3$$

$$V_{tot} = V_1 + V_2 + V_3$$

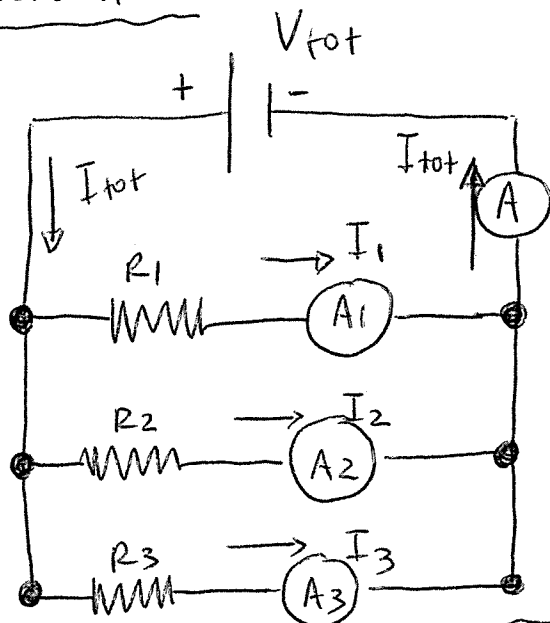
$$R_{tot} = R_1 + R_2 + R_3$$

$$* R_{tot} > R_{(max)}$$

* the greater the R_{tot}
the lower the I_{tot}

Adding more resistors in series will result in the significant drop of the I_{tot} (Circuit doesn't function)

Parallel



$$I_{tot} = I_1 + I_2 + I_3$$

$$V_{tot} = V_1 = V_2 = V_3$$

$$\frac{1}{R_{tot}} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3}$$

$$* R_{tot} < R_{(min)}$$

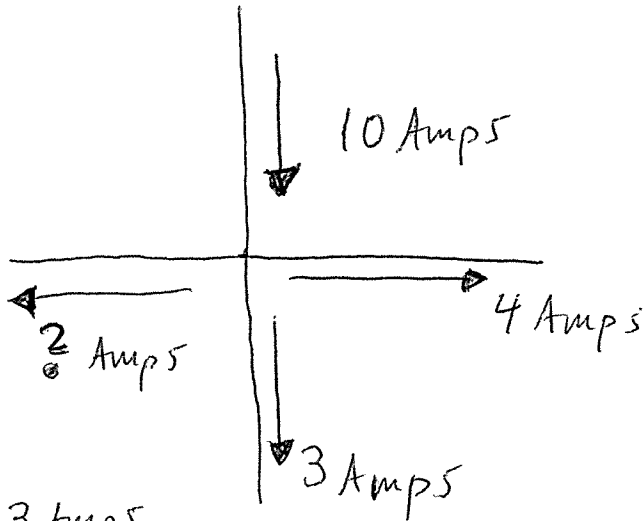
• junction → current splits

* the more resistors we add in parallel, the lower the R_{tot} and higher the I_{tot} . That can cause overloading (FIRE)

Conservation of Current

* the total Current (I) that arrives at a junction, is equal to the total current (I) that leaves from the junction

ex.



Answer: 3 Amps

Why? $(3 + 4 + 3) \text{ Amps} = 10 \text{ Amps}$

Meters

(A) : Ammeter : connected in series
possesses zero or very low resistance

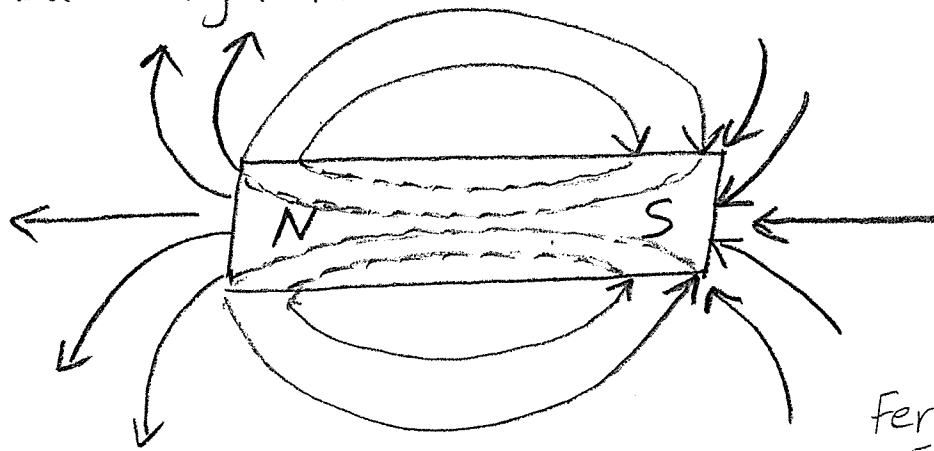
(V) : Voltmeter : connected in parallel
possesses infinite or very high resistance

Magnetism Review Notes

- * Moving charges create Magnetism
- * Natural Magnetism comes from spinning electrons in atoms
- * Moving magnets create electric current

Magnetic Fields : regions where magnetic forces may be detected

* Bar Magnets

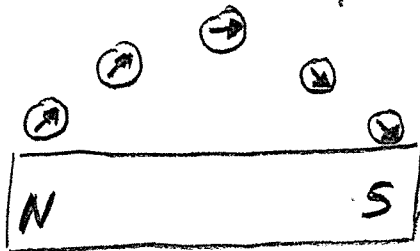


Magnetic Flux

Lines : lines of magnetism in a magnetic field

Ferromagnetic Elements : Co (COBALT)
Fe (IRON)
Ni (NICKEL)

- * the needles of a compass line up perfectly with the flux lines
- * the arrows on a flux line show where the North Pole of a compass would point in the field

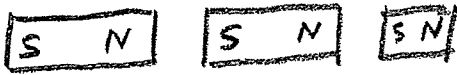
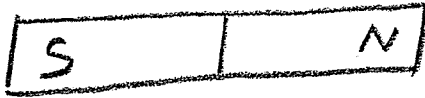


Flux arrows point
"OUT of NORTH
INTO SOUTH"

Magnetic force is strongest at the POLES where flux lines are closest.

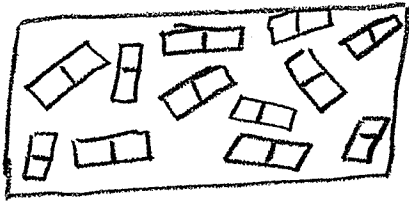
- * Magnetic flux lines never cross and are closed loops that start from the NP to the SP and pass through, 23

Cutting Magnets → each piece is a brand new magnet



Magnets attract non-magnets

* Certain metals contain magnetic regions called domains. They are randomly orientated



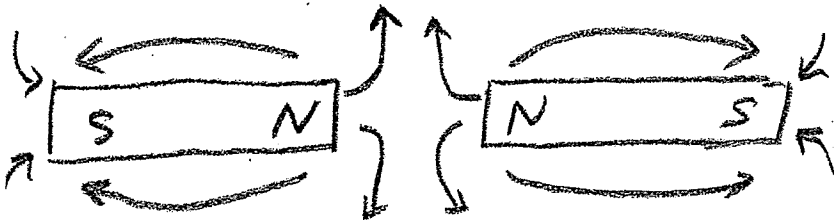
Domains are spinning electrons that create small magnetic fields and act like small magnets. The fields cancel each other

but when a bar magnet comes closer then →

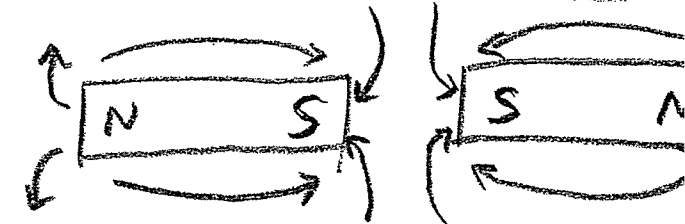


the magnetic domains line up with the magnet. The metal is magnetized

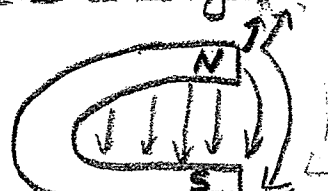
Magnetic Flux Lines
between two magnets



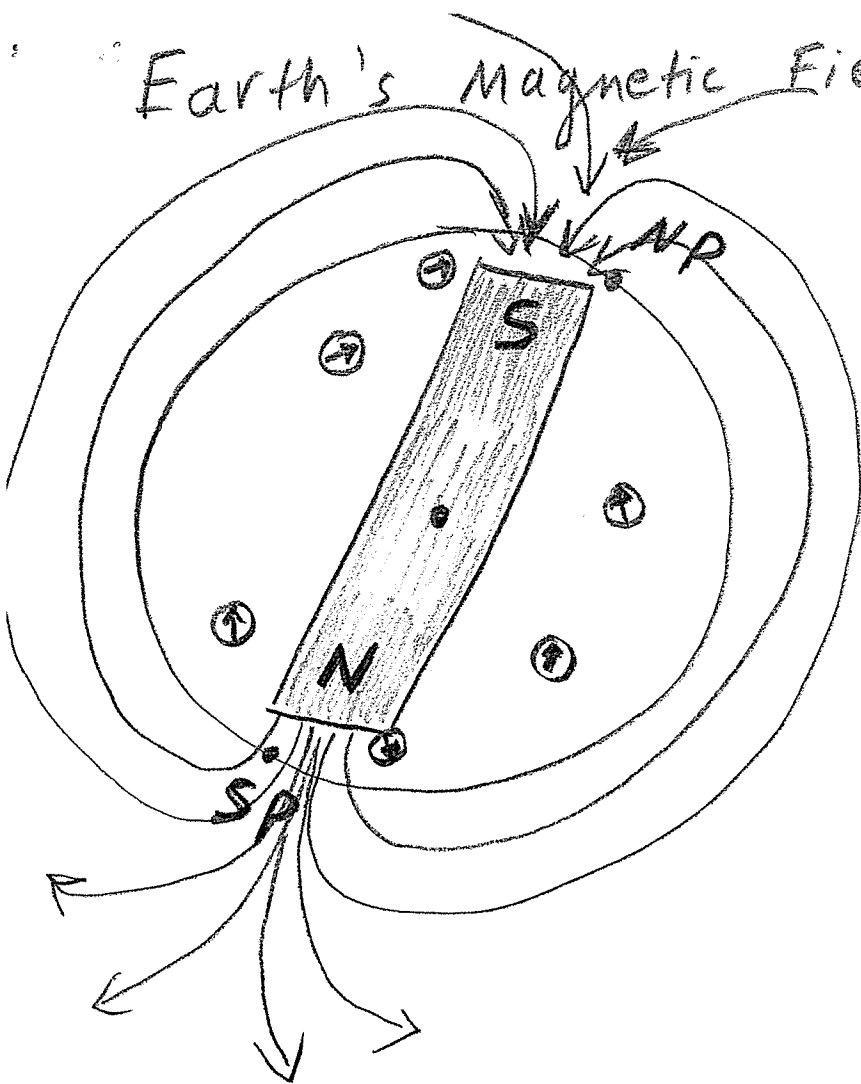
ex: paper clips attracted to a bar magnet.



Horseshoe Magnet



Earth's Magnetic Field



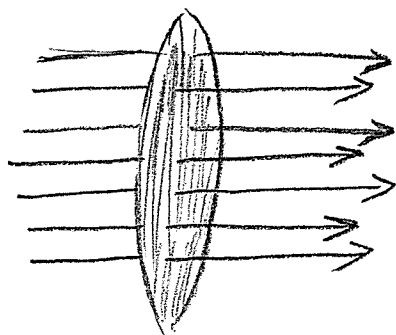
A compass points to the North Geographic Pole which is close to the South Magnetic Pole.

Earth's Magnetic Field : Reversed Polarity

Magnetic Field strength (B) is the number of magnetic flux lines per unit area passing through a plane perpendicular to the direction of the Lines
Unit : Teslas Type of Quantity : Vector

Number of lines of flux
Unit : Weber (wb)

$$1 \text{ Tesla} = 1 \frac{\text{Weber}}{\text{m}^2}$$



Electromagnetic Radiation :
accelerating electric charges
produce changing
electric and magnetic
fields

Waves: Disturbances that move through space or through a medium (material) and transfer Energy, no mass

Wave Classification:

Transverse: particles move perpendicular to the direction of the wave (up and down) ex light, ocean waves

Longitudinal: particles move parallel to the direction of the wave (side to side) ex sound,

Mechanical: Require medium (sound waves can not be transmitted in empty space)

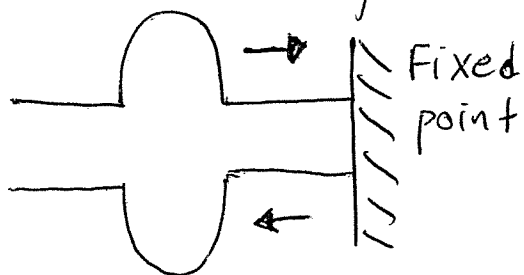
Electromagnetic: Do not require medium (light waves can travel through empty space)

Light waves are transverse and electromagnetic

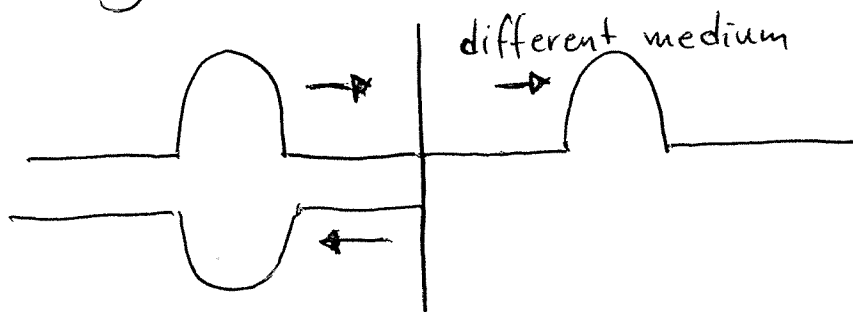
Sound waves are longitudinal and mechanical

Wave Pulses: single vibratory disturbances

Behavior of pulses



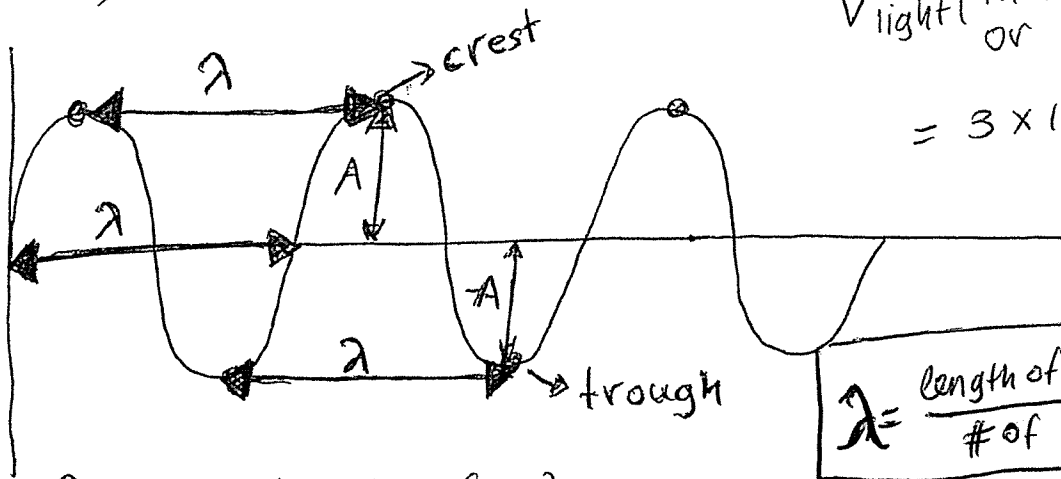
pulse is reflected and inverted



pulse is partially transmitted and partially reflected and partially absorbed

Waves / Characteristics

Types: A) Transverse (ex light)



$$V_{\text{light}} (\text{in vacuum or air}) = 3 \times 10^8 \frac{\text{m}}{\text{s}}$$

$$\lambda = \frac{\text{length of wave train}}{\text{\# of cycles}}$$

λ = wavelength (m)

f = frequency (Hz)

T = Period (T)

$$T = \frac{1}{f} \quad f = \frac{1}{T}$$

$$f = \frac{\text{\# of cycles}}{\text{time}}$$

$$T = \frac{\text{time}}{\text{\# of cycles}}$$

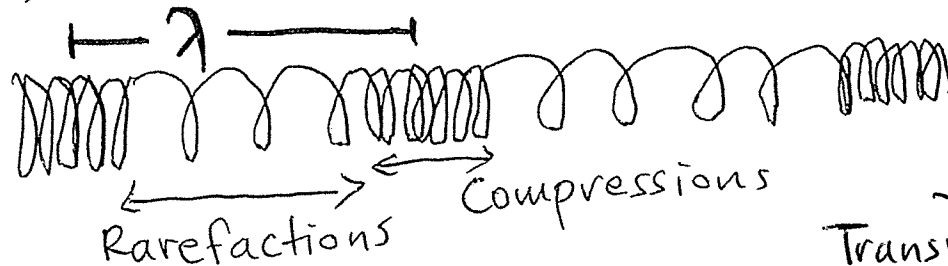
V = velocity of a wave ($\frac{\text{m}}{\text{s}}$)

$$V = \lambda \cdot f$$

$$V = \frac{\lambda}{T}$$

$$V = \frac{d}{t}$$

B) Longitudinal (ex sound)



Definitions of

Transverse waves: up and down

Longitudinal waves: side to side

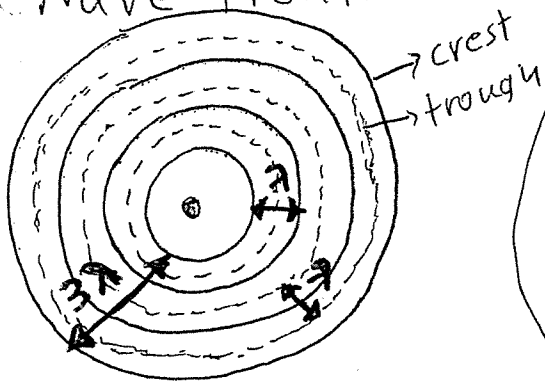
Mechanical waves: need medium

Electromagnetic waves: do not need medium

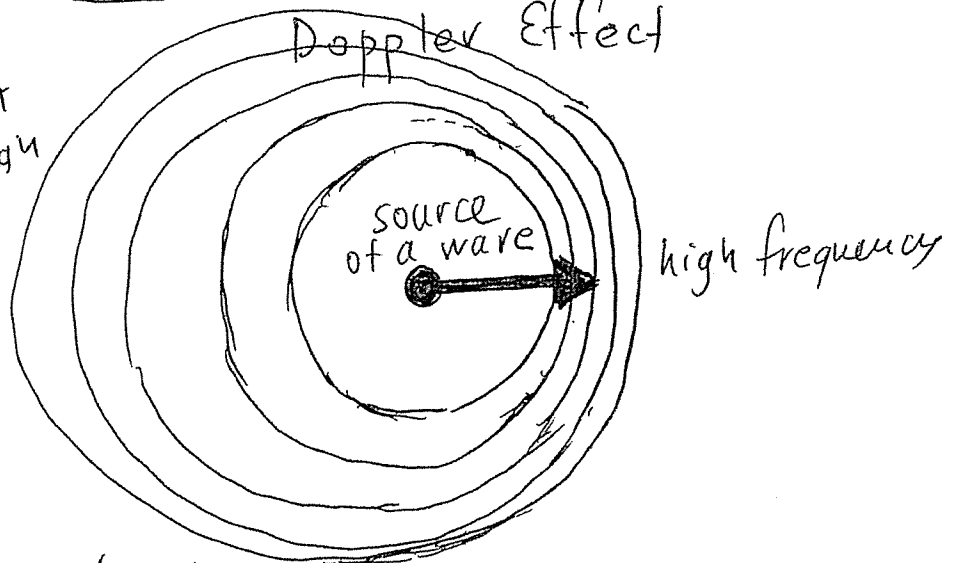
$$V_{\text{sound}} (\text{in air}) = 331 \frac{\text{m}}{\text{s}}$$

Wave Phenomena

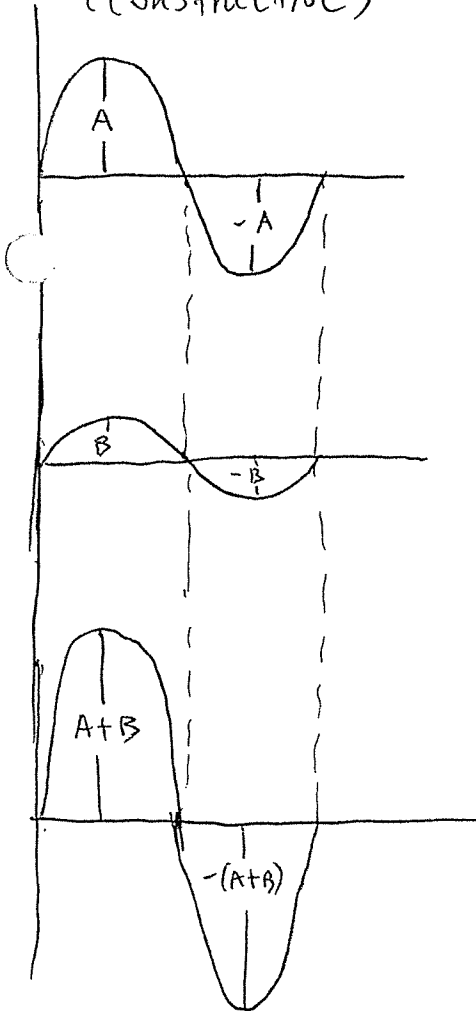
Wave fronts



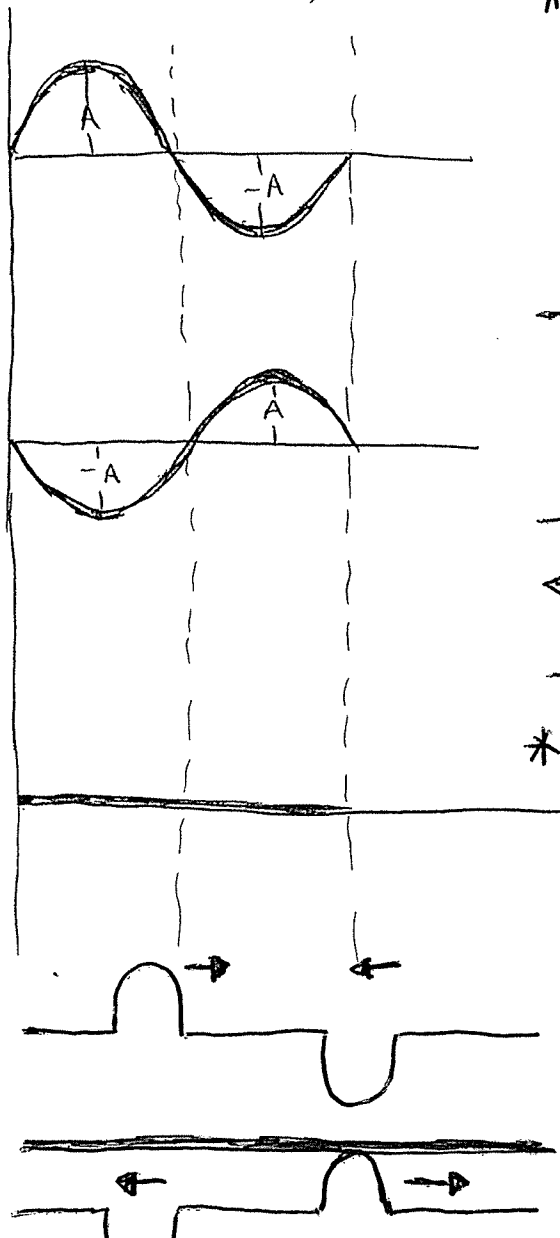
Doppler Effect



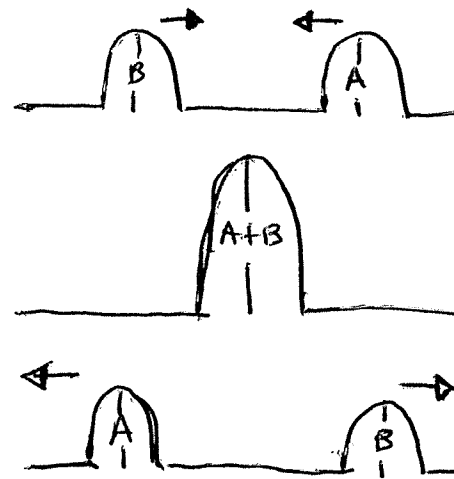
Interference (Constructive)



(Destructive)



* more pictures on interference with pulses

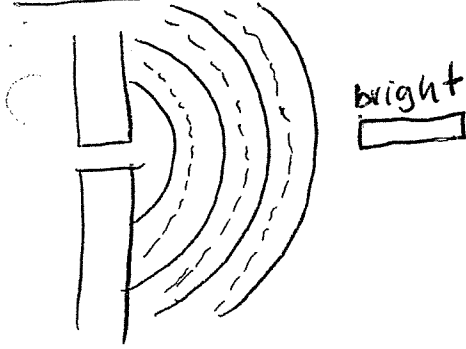


* Constructive

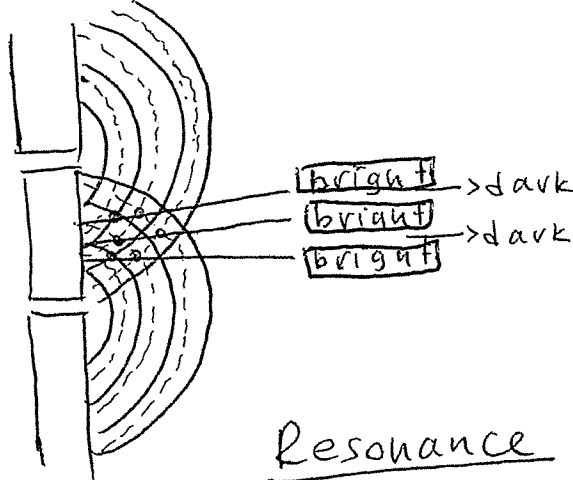
Destructive

↑ Principle of Superposition

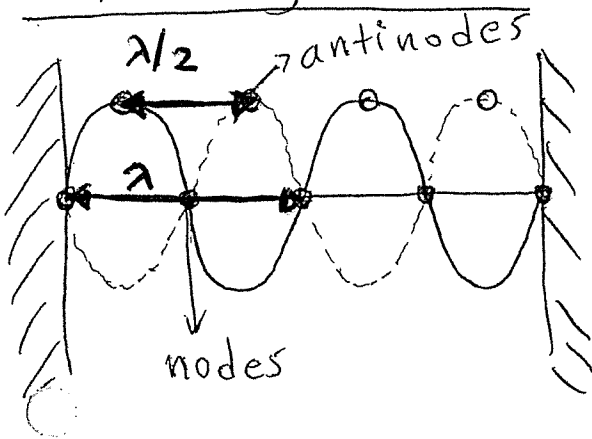
Diffraction



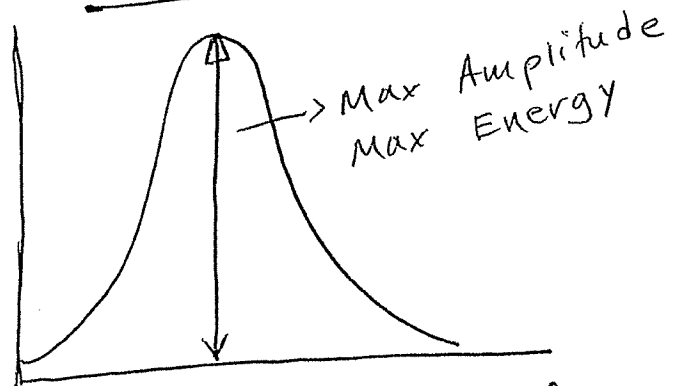
Double slit Diffraction



Standing Waves



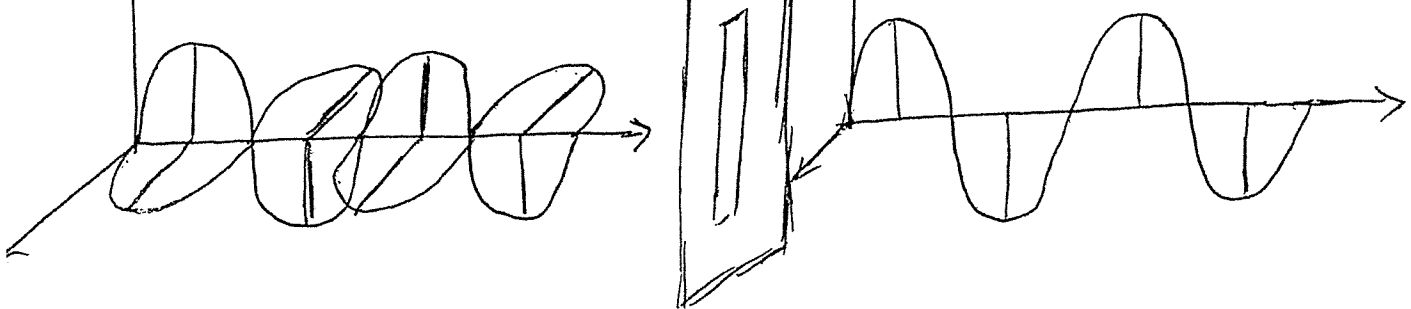
Resonance



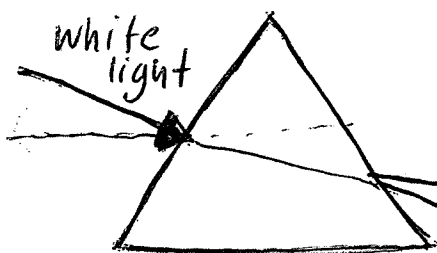
frequency of vibration = Natural frequency of the object

Polarization

* occurs only in transverse waves



Dispersion

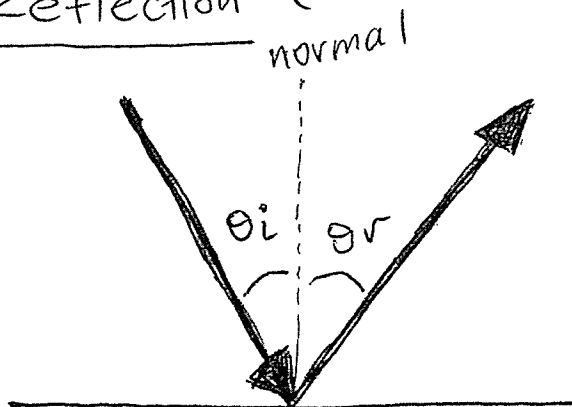


Red $\rightarrow$ big $\lambda \rightarrow$ big $\checkmark$
Violet $\rightarrow$ small $\lambda \rightarrow$ small $\checkmark$

Red (fastest color - bends the least)

Violet (slowest color - bends the most)

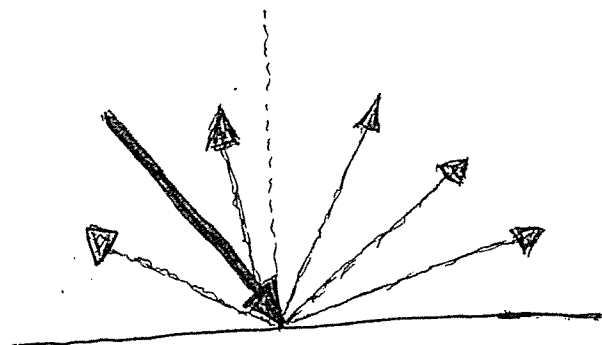
Reflection (makes a V)



θ_i = angle of incidence

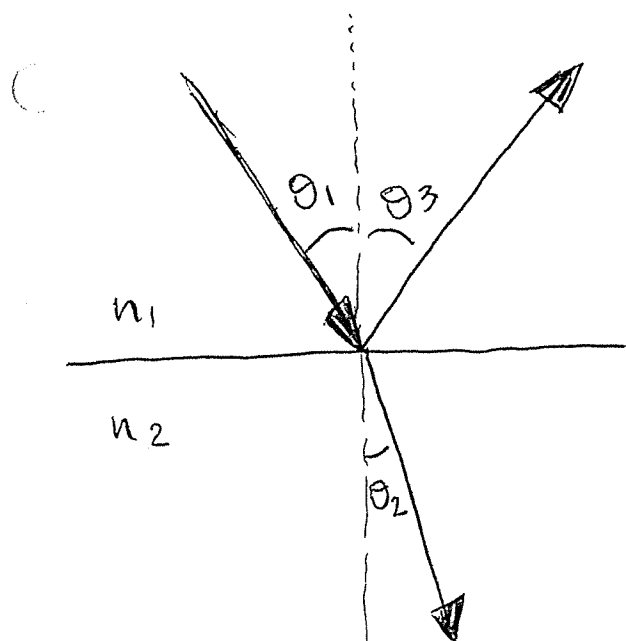
θ_r = angle of reflection

$\theta_i = \theta_r$: Law of Reflection



Random or Diffuse Reflection

Refraction



θ_1 = angle of incidence

θ_3 = angle of reflection

θ_2 = angle of refraction

n : index of Refraction (see R.T.)

$$n = \frac{c}{v}$$

c : speed of light in vacuum or air
($3 \times 10^8 \frac{m}{s}$)

v : speed of light in a different medium

$\theta_1 = \theta_3$ (θ_3 : Reflected Ray)

Snell's Law

$$n_1 \sin \theta_1 = n_2 \sin \theta_2$$

if $n_2 > n_1$ medium 2 : slow
medium 1 : fast

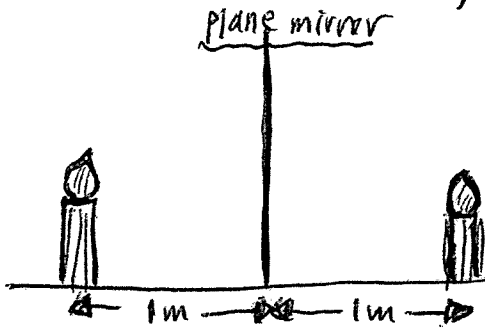
$\theta_2 < \theta_1$ Refracted Ray bends towards the normal

if $n_2 < n_1$ medium 2 : fast
medium 1 : slow

$\theta_2 > \theta_1$ Refracted Ray bends away from the normal.

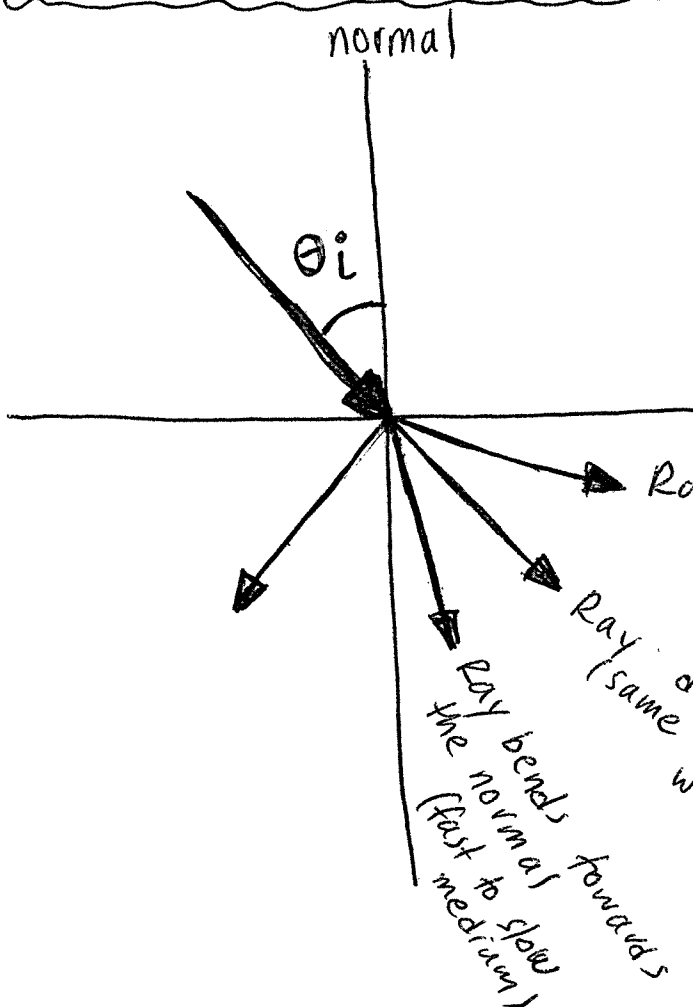
More on Reflection

- * Plane mirrors do not produce a real image. Image is virtual, upright, same size as object and is found behind the mirror, equal distance as the object from the mirror



- * A person with a certain height h needs a mirror half his size to see his whole body reflection in the mirror

More on Refraction



Relationship between n and v

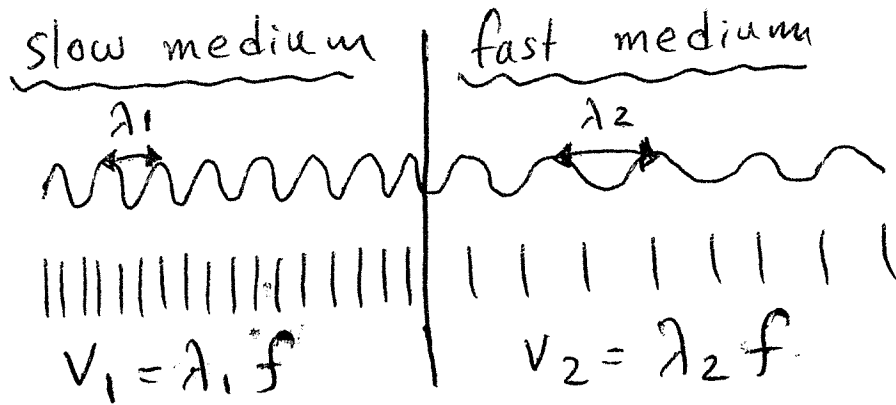
$$n = \frac{c}{v}$$

$$v = \frac{c}{n}$$



* During Refraction $\rightarrow$ frequency doesn't change

* color doesn't change
if v increases then ($v = \lambda f$) λ increases as well



if $v_2 > v_1$
then $\lambda_2 > \lambda_1$

$$\frac{n_2}{n_1} = \frac{\frac{c}{v_2}}{\frac{c}{v_1}} = \frac{v_1}{v_2} = \frac{\lambda_1}{\lambda_2}$$

* equations used
when n_s and v_s
are given or
 n_s and λ_s

More on Wave Phenomena (Definitions)

Doppler Effect: variation in the observed frequency of a wave when there is relative motion between the source of the wave and the receiver

Interference: effect produced by two waves passing simultaneously through a region

Diffraction: the spreading out of a wave into the region behind an obstacle

Standing waves: waves produced when two waves of the same frequency and amplitude travel in opposite directions in the same medium

Resonance: the building up of energy by adding small amounts of energy in time with the natural frequency of an object

Modern Physics

light

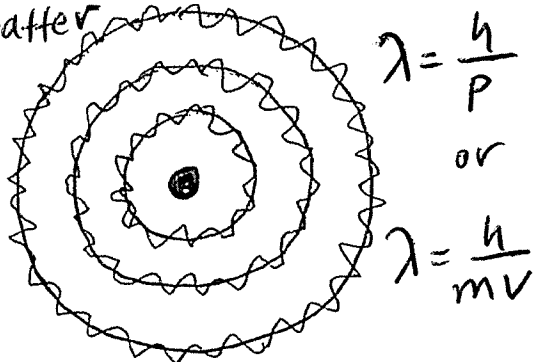
wave

particle

- Diffraction
- Doppler Effect
- Standing Waves
- Resonance
- Interference
- Photoelectric Effect
- Compton Scattering

De Broglie Waves

* (electron waves)
or matter



Bohr's Model

$$E_{\text{(electron)}} = hf \text{ (eV)}$$

$$\text{(eV)} \xrightarrow{\times 1.6 \times 10^{-19}} \text{Joules}$$

$$\div 1.6 \times 10^{-19}$$

$$f = \frac{E \text{ (Joules)}}{h \text{ (J.s)}} \Rightarrow \text{(Hz)}$$

Energy of a photon

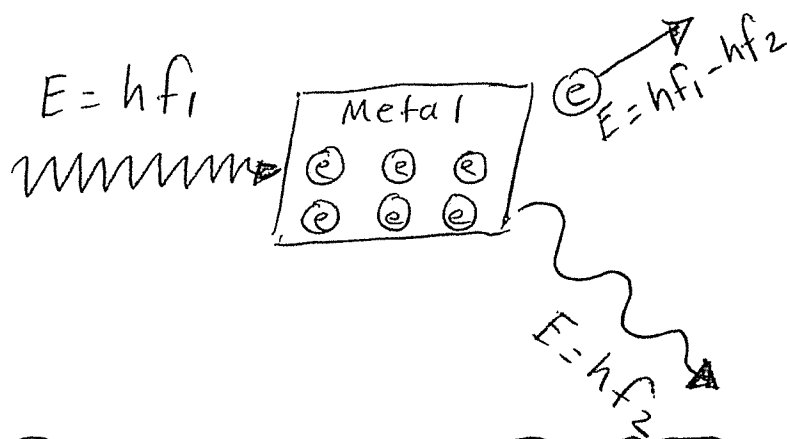
$$E = hf = \frac{hc}{\lambda}$$

h : Planck's Constant
 $6.63 \times 10^{-34} \text{ J.s.}$

Photoelectric Effect



Compton Scattering



$$E = mc^2$$

$$m \rightarrow \text{kg} \quad c^2 = 9 \times 10^{16} \frac{\text{m}^2}{\text{s}^2}$$

$$E \rightarrow \text{Joules}$$

$$1 \text{ amu} = \frac{1}{12} \text{ of } {}^{12}_6\text{C} = 9.31 \times 10^2 \text{ MeV}$$

$$\text{Binding Energy} = \text{Mass Defect} * c^2$$

Strong (Nuclear Force) → strong (short range) force that holds the nucleons together (protons and neutrons)

* Strong Force is 100 x stronger than Electrostatic Force and 10^{38} x stronger than Gravitational Force.

Standard Model (Classification of Particles)

(see R.T)

Hadrons → Baryons (ex proton (uud), neutron (ddu))
3 quarks in each baryon

→ Meson (ex $u\bar{d}$, $s\bar{c}$) 1 quark and 1 anti-quark

Leptons → electron (e), positron ($\bar{e}$)

(All hadrons or leptons have a charge that is a multiple integer of the elementary charge (e))

* $e = 1.6 \times 10^{-19} \text{ C}$

Only quarks have a charge that is a portion of the elementary charge (ex $+\frac{1}{3}e$ or $-\frac{2}{3}e$) but quarks can not be found free in nature.

They always come in a packet of three or two.

a packet of 3 quarks is a baryon

a packet of 2 quarks (quark + antiquark) is a meson

Neutrons and neutrinos are neutral. Their antiparticles have an opposite spin.

Antiparticles have the same symbol as the corresponding particles, they take a bar (-) on top ex p and $\bar{p}$ (proton and antiproton) (24)

UNITS

v : velocity $-(\frac{m}{s})$
 a : acceleration $-(\frac{m}{s^2})$
 d : displacement $-(m)$
 F : force - Newton $=(kg \cdot \frac{m}{s^2})$
 m : mass $-(kg)$
 μ : coefficient of friction (no unit)
 g : gravitational acceleration $(9.8 \frac{m}{s^2})$
 or gravitational field strength
 p : momentum $-(kg \cdot \frac{m}{s} \text{ or } N \cdot s)$
 J : impulse $-(N \cdot s \text{ or } kg \cdot \frac{m}{s})$
 K : spring constant $-(\frac{N}{m})$
 KE : Kinetic Energy (J) - Joule
 PE : Potential Energy (J) - Joule
 W : Work (J) - Joule
 P : Power (Watt)
 E_T : total energy (J) - Joule
 Q : internal energy (J) - Joule
 F_e : Electrostatic force (N)
 E : Electric field strength $(\frac{N}{C})$
 V : Potential Difference (V) - Volt
 I : Electric current (A) - Ampere
 R : Resistance (Ω - Ohms) ρ : resistivity ($\Omega \cdot m$)

Q : charge (C) Coulomb
 f : frequency (Hz)
 λ : wavelength (m)
 T : period (sec)
 n : index of Refraction (no unit)
 c : $3 \times 10^8 \text{ m/s}$

* Vector Quantities
 velocity
 displacement
 acceleration
 force / weight
 Impulse
 momentum
 Electric field strength

* Scalar Quantities
 speed
 distance
 mass
 frequency
 period
 energy / work
 power

$$1 \text{ Joule} = 1 \text{ N} \cdot \text{m} = 1 \text{ kg} \frac{\text{m}}{\text{s}^2} \text{m} = 1 \text{ kg} \frac{\text{m}^2}{\text{s}^2}$$

$$1 \text{ kg} \frac{\text{m}}{\text{s}} = 1 \text{ N} \cdot \text{s}$$

$$1 \text{ Watt} = 1 \frac{\text{Joule}}{\text{sec}} = 1 \frac{\text{N} \cdot \text{m}}{\text{sec}} = 1 \text{ kg} \frac{\text{m}}{\text{s}^2} \frac{\text{m}}{\text{s}} = 1 \text{ kg} \frac{\text{m}^2}{\text{s}^3}$$

$$\text{Inertia (no units)} \sim \text{Mass (kg)}$$

$$1 \text{ Volt} = 1 \text{ Amp} \cdot \text{ohm}$$

$$1 \text{ Amp} = 1 \frac{\text{Coulomb}}{\text{sec}}$$

$$1 \text{ Watt} = 1 \text{ Volt} \cdot \text{Amp}$$

$$1 \text{ Volt} = 1 \frac{\text{Joule}}{\text{Coulomb}}$$

$$1 \text{ Hz} = \frac{1}{\text{sec}}$$

$$1 \text{ sec} = \frac{1}{\text{Hz}}$$

$$\frac{\text{m}}{\text{s}} = \text{m} \cdot \text{Hz}$$

$$1 \text{ Joule} = 1 \text{ kg} \frac{\text{m}^2}{\text{s}^2}$$

$$1 \text{ Joule} = 6.25 \times 10^{18} \text{ eV}$$

$$1 \text{ C} = 6.25 \times 10^{18} \text{ e}$$

$$1 \text{ eV} = 1.6 \times 10^{-19} \text{ J}$$

$$1 \text{ e} = 1.6 \times 10^{-19} \text{ C}$$

$$1 \text{ u} = 9.31 \times 10^2 \text{ MeV}$$